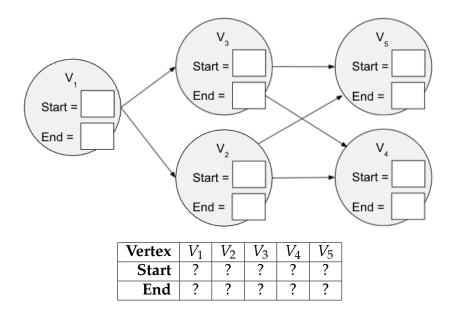
Collaboration Policy: You are encouraged to collaborate with up to 3 other students, but all work submitted must be your own *independently* written solution. List the computing ids of all of your collaborators in the collabs command at the top of the tex file. Do not share written notes, documents (including Google docs, Overleaf docs, discussion notes, PDFs), or code. Do not seek published or online solutions for any assignments. If you use any published or online resources (which may not include solutions) when completing this assignment, be sure to cite by naming the book etc. or listing a website's URL. Do not submit a solution that you are unable to explain orally to a member of the course staff. Any solutions that share similar text/code will be considered in breach of this policy. Please refer to the syllabus for a complete description of the collaboration policy.

Collaborators: list collaborators's computing IDs

Sources: Cormen, et al, Introduction to Algorithms. (add others here)

PROBLEM 1 DFS and Topological Sort

1. Run DFS on the following graph. List start and finish times (beginning at t=1) for each node in the table shown below the image of the graph. Note: For this problem, by "start" we mean the discovery time, and by "end" we mean finish times.) Use V_1 as your start node. To help us grade this more easily, when multiple nodes can be searched, always search neighboring nodes in increasing order (e.g., if V_2 and V_3 are both adjacent to the current node, search V_2 first).



Solution: Your answer here!

2. Using your answer above, give the specific *Topological Ordering* that would be produced by the *DFS-based* algorithm we discussed in class.

Solution: Your answer here!

PROBLEM 2 True or False. (You don't have to explain this in your submission, but you should understand the reason behind your answer.)

A. If you use DFS to find a topological sorting on a directed graph, the last vertex discovered in the search could legally be the last vertex in the sorted ordering of the vertices. *Update:* Assume your first call to DFS-visit() visits every node in the digraph!

Solution: Your answer here!

B. For the disjoint set data structure we studied, if we had a $\Theta(\log n)$ implementation of *find-set*(), then the order class for the time-complexity of union(i,j) would be improved (i.e., better than the result we learned).

Solution: Your answer here!

C. Both path-compression and union-by-rank try to improve the cost of future calls to *find-set()* by making the trees representing a set shorter without changing the set membership for the items in that set.

Solution: Your answer here!

PROBLEM 3 Kruskal's Runtime

What is the runtime of Kruskal's algorithm if find() and union() are $\Theta(1)$ time?

Solution: Your answer here!

PROBLEM 4 Strongly Connected Components

Your friend Kai wants to find a digraph's SCCs by initially creating G_T and running DFS on that. In other words, he believes he might be able to *first* do something with the transpose graph as the first step for finding the SCCs. (The algorithm we gave you first did something with G and not with G_T .)

Do you think it's possible for Kai to make this approach work? If not, describe a counter-example or explain why this will fail.

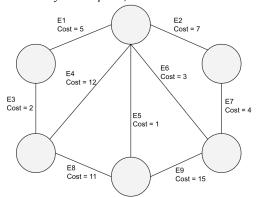
If it is possible, explain the steps Kai's algorithm would have to do to complete the algorithm, and briefly say why this approach can lead to a correct solution.

Solution: Your answer here!

PROBLEM 5 Executing Kruskal's MST Algorithm

Run Kruskal's algorithm on the graph below. List the order in which the edges are added to the MST, referring to the edges by their provided labels.

(Consider how your answer would change if E1 had weight 12. However, you don't need to provide an answer to us for this part.)



Your answer (list of edges in order):

Solution: Your answer here!

PROBLEM 6 Difference between Prim's MST and Dijkstra's SP

In a few sentences, summarize the relatively small differences in the code for Prim's MST algorithm and Dijkstra's SP algorithm.

Solution: Your answer here!

PROBLEM 7 True or False. (You don't have to explain this in your submission, but you should understand the reason behind your answer.)

A. An *indirect heap* makes *find()* and *decreaseKey()* faster (among others), but *insert()* becomes asymptotically slower because the indices in the indirect heap must be updated while percolating value up towards the root of the heap.

Solution: Your answer here!

B. If all edges in an undirected connected graph have the same edge-weight value k, you can use either BFS or Dijkstra's algorithm to find the shortest path from s to any other node t, but one will be more efficient than the other.

Solution: Your answer here!

C. In the proof for the correctness of Dijkstra's algorithm, we learned that the proof fails if edges can have weight 0 because this would mean that another edge could have been chosen to another fringe vertex that has a smaller distance than the fringe vertex chosen by Dijkstra's. **Solution:** Your answer here!

PROBLEM 8 Gradescope Submission

Submit a version of this .tex file to Gradescope with your solutions added, along with the compiled PDF. You should only submit your .pdf and .tex files.