

CS 3100

Data Structures and Algorithms 2

Lecture 22: Reductions

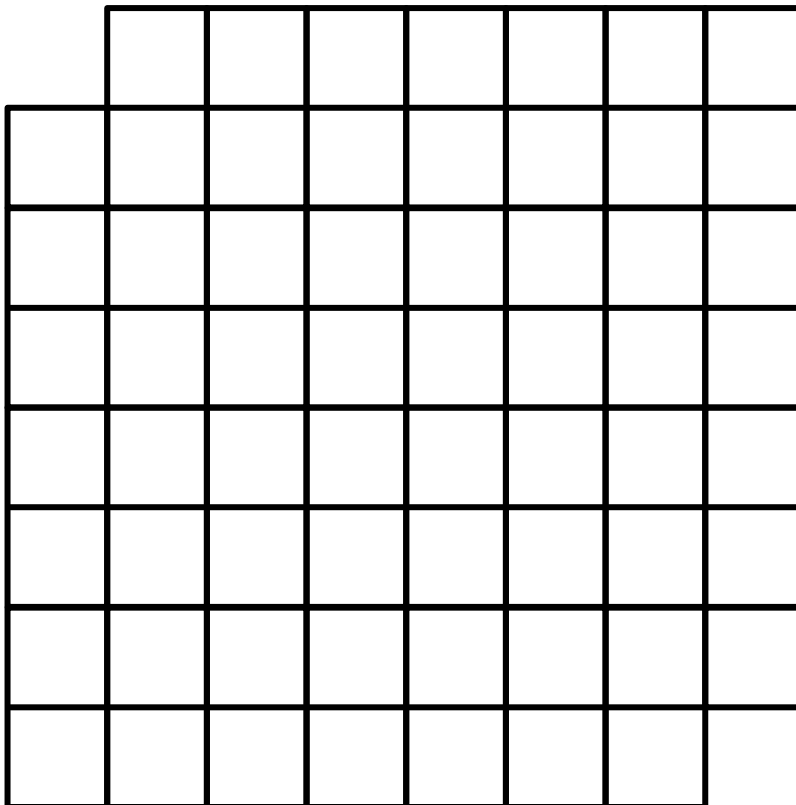
Co-instructors: Robbie Hott and Ray Pettit
Spring 2024

Readings from CLRS 4th Ed: Network flow etc. in Chapter 24
(Reductions covered in CLRS but in a context we're not studying in CS3100)

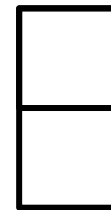
Warm-Up

Can you fill a 8×8 board with the corners missing using dominoes?

Can you tile this?



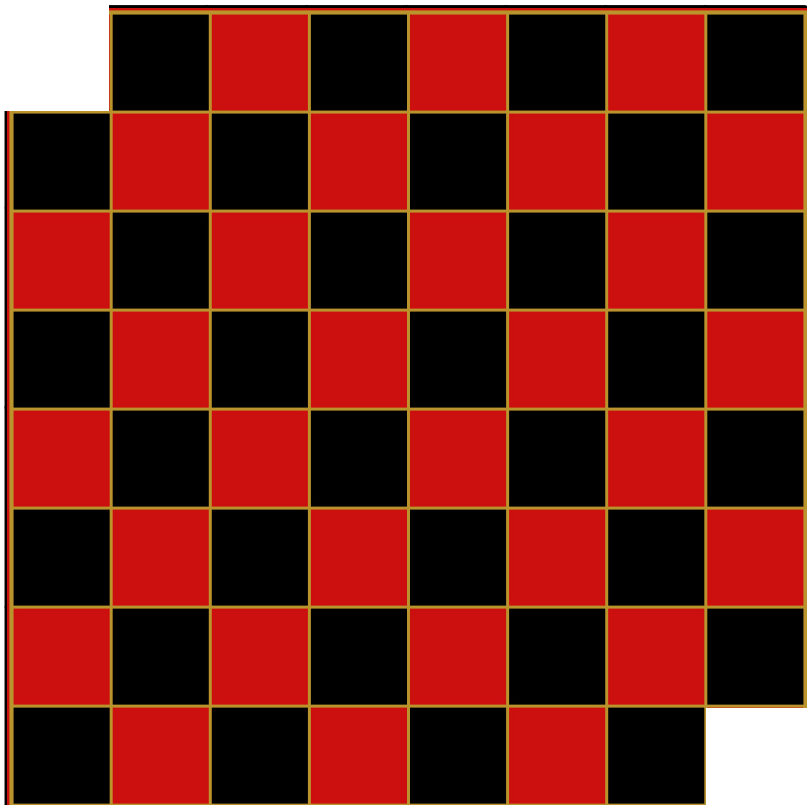
With these?



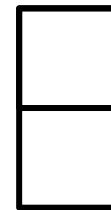
Warm-Up

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With these?

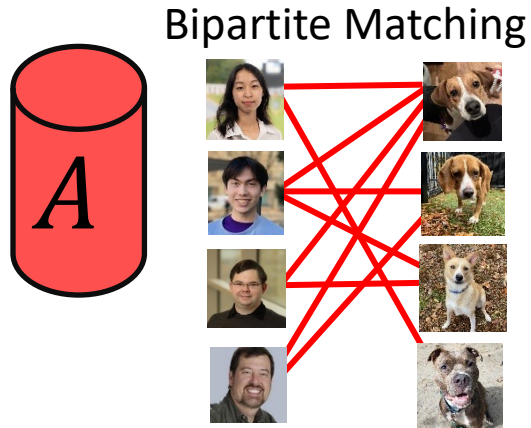


Reductions

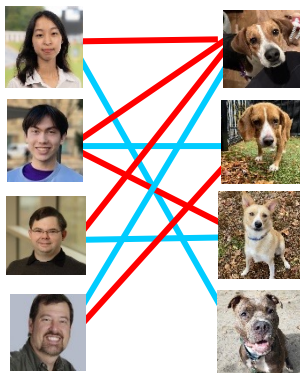
- Algorithm technique of supreme ultimate power
- Convert instance of problem A to an instance of Problem B
- Convert solution of problem B back to a solution of problem A

Bipartite Matching Reduction

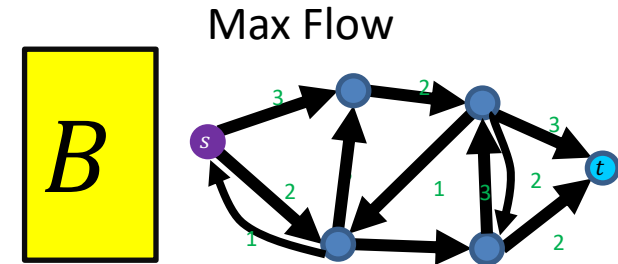
Problem we don't know how to solve



Solution for A

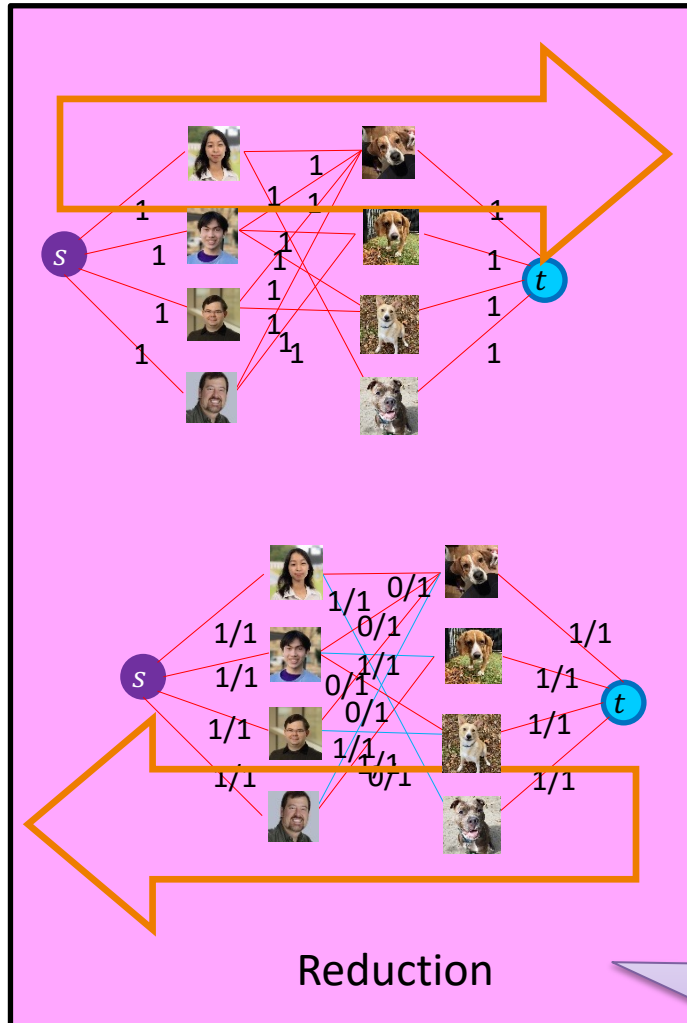
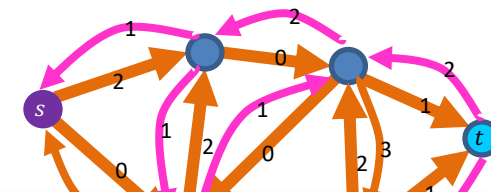


Problem we do know how to solve



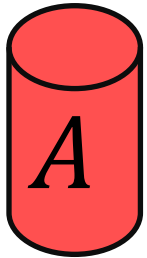
Ford Fulkerson

Solution for B



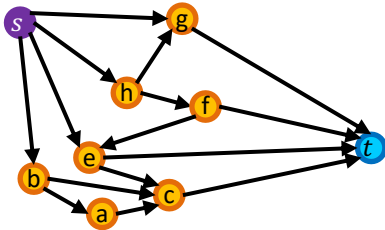
Must show (prove):
 1) how to make construction
 2) Why it works

Edge Disjoint Paths Reduction

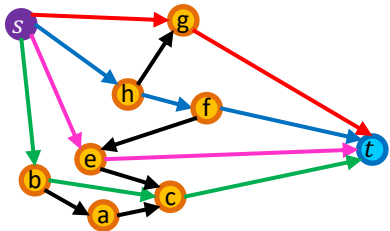


Problem we don't know how to solve

Edge Disjoint Paths

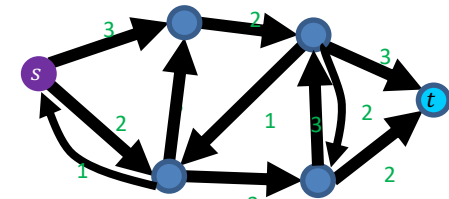
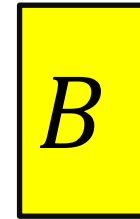


Solution for *A*



Problem we do know how to solve

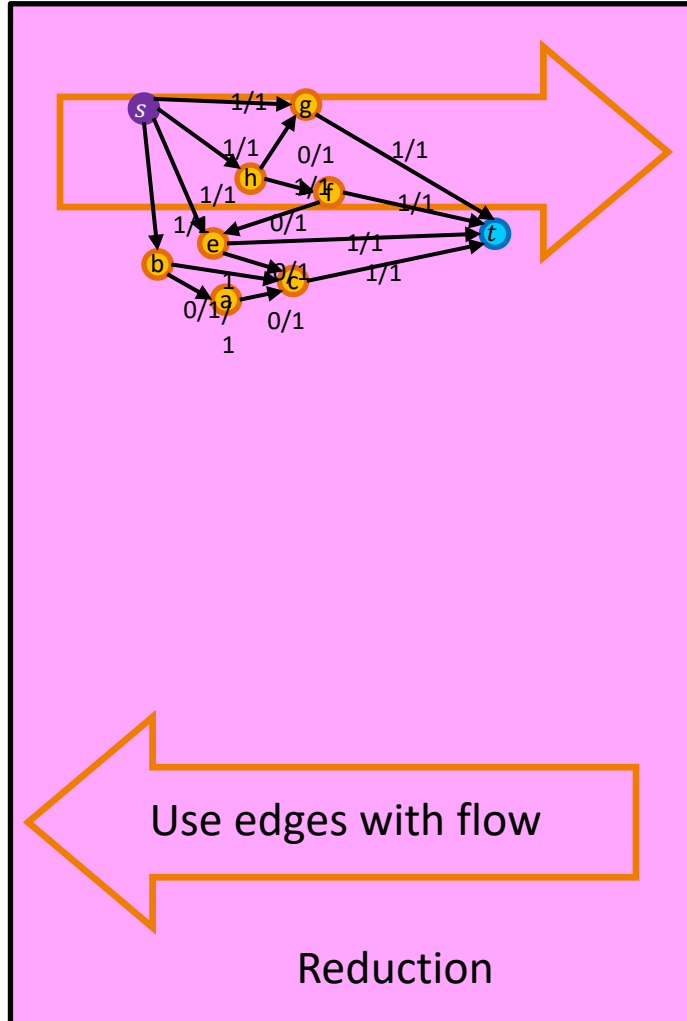
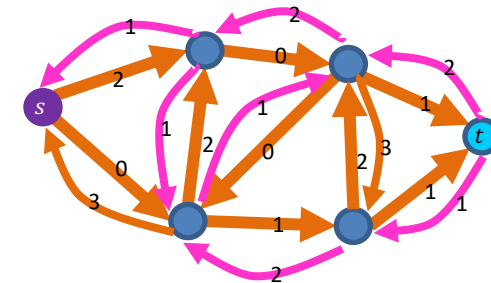
Max Flow



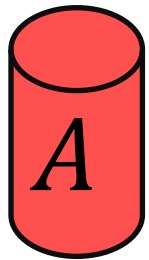
Ford Fulkerson



Solution for *B*

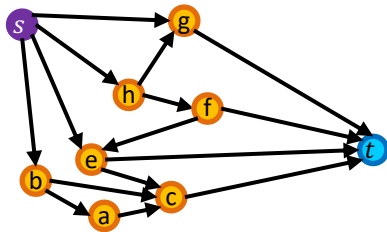


Vertex Disjoint Paths Reduction

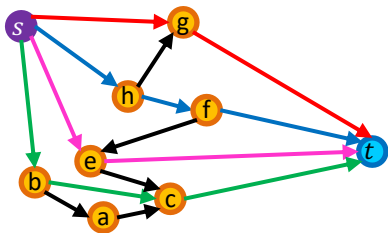


Problem we don't know how to solve

Vertex Disjoint Paths

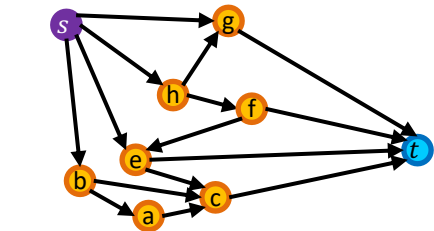


Solution for *A*

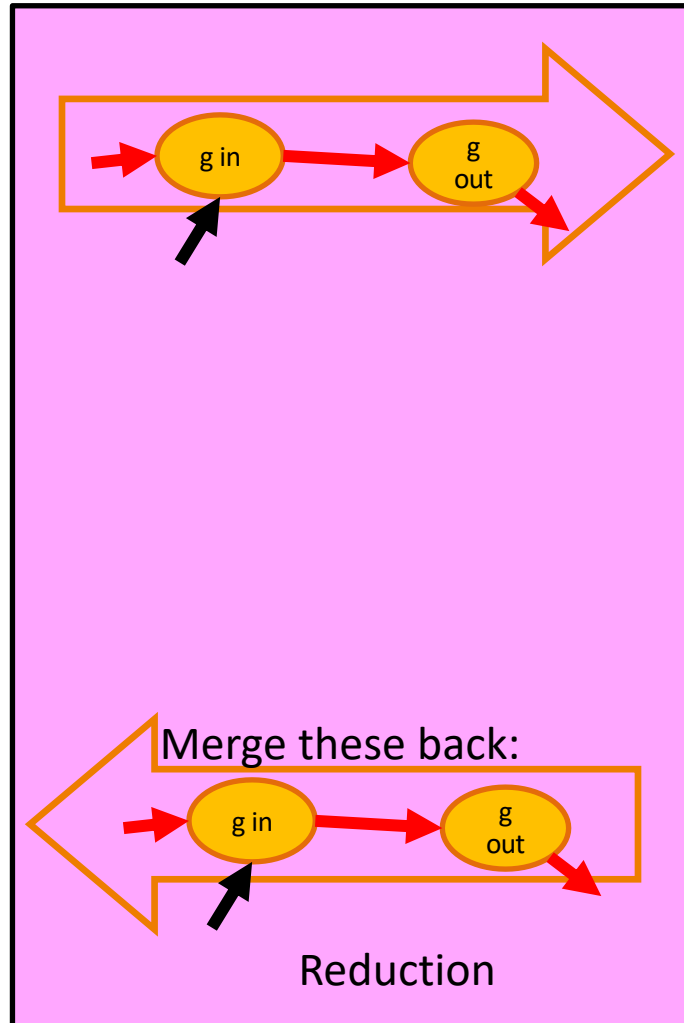
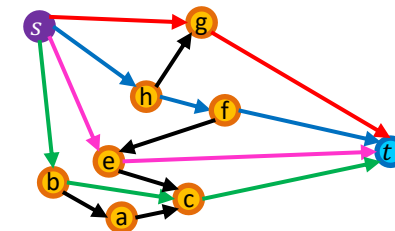


Problem we do know how to solve

Edge Disjoint Paths

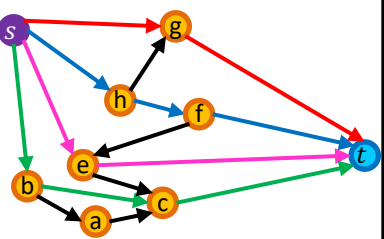
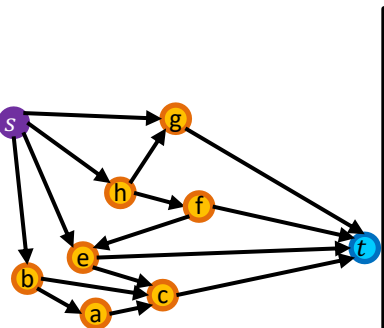


Solution for *B*

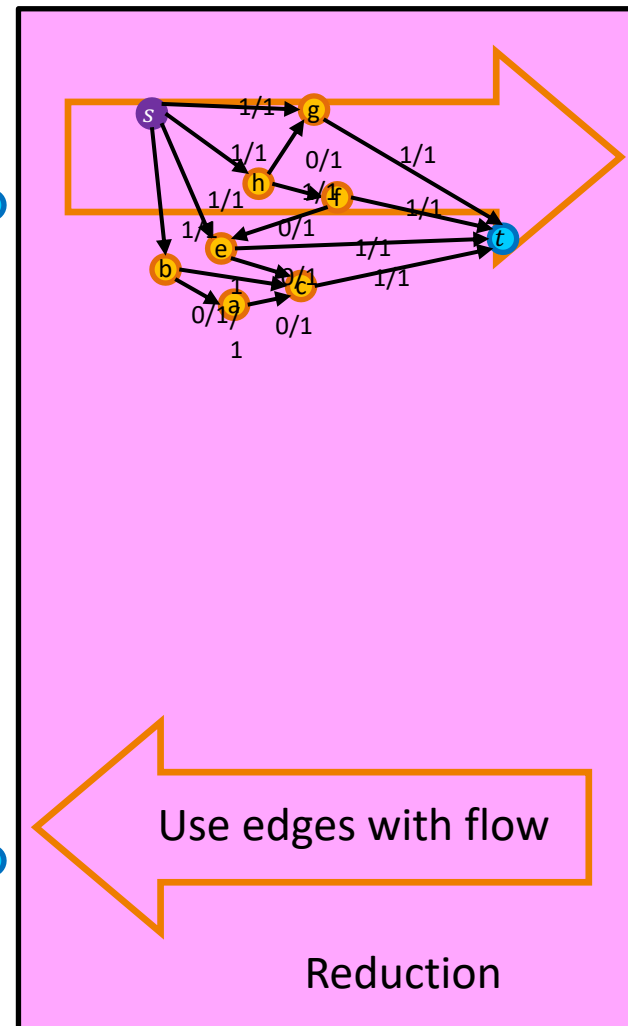
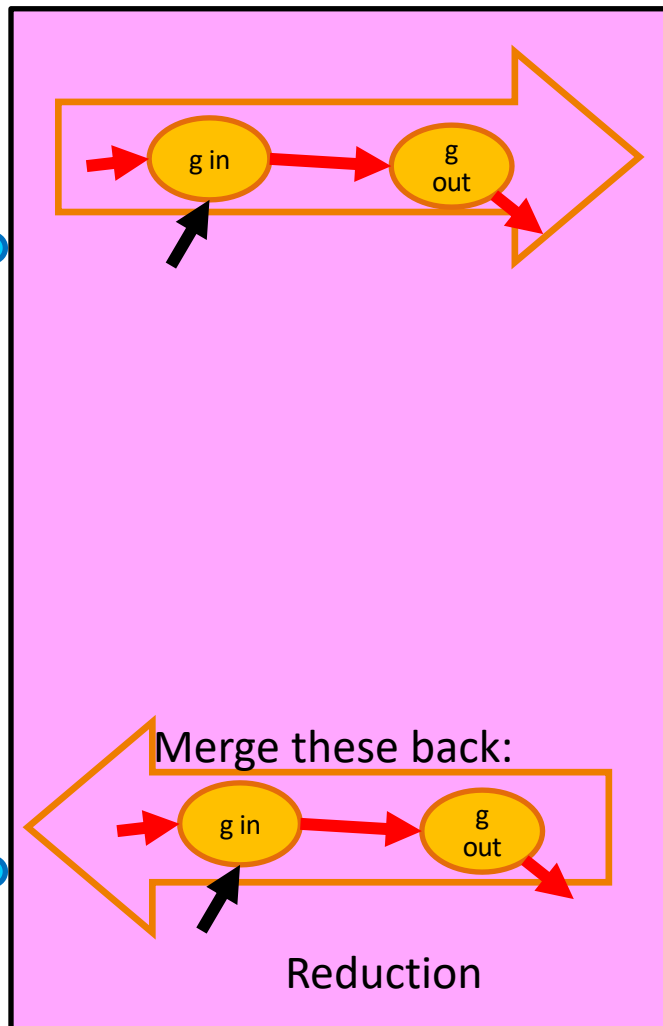
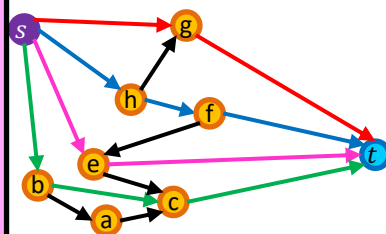
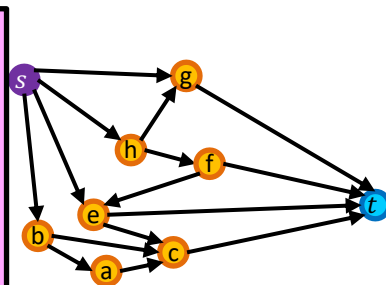


Vertex Disjoint Paths Big Picture

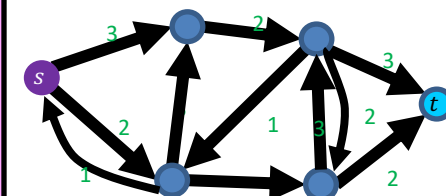
Vertex Disjoint Paths



Edge Disjoint Paths

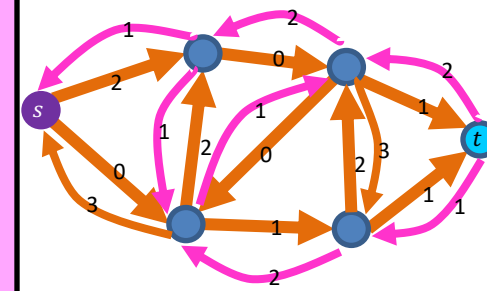


Max Flow



Ford Fulkerson

Solution for B

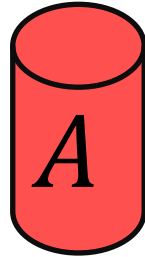


Reductions for New Algorithms

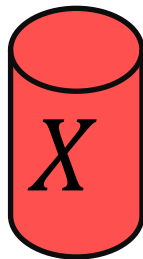
- Create an algorithm for a new problem by using one you already know!
- More algorithms = More opportunities!
- The problem you reduced to could itself be solved using a reduction!

In General: Reduction

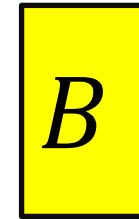
Problem we don't know how to solve



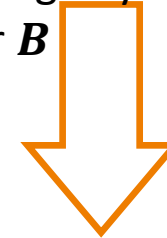
Solution for A



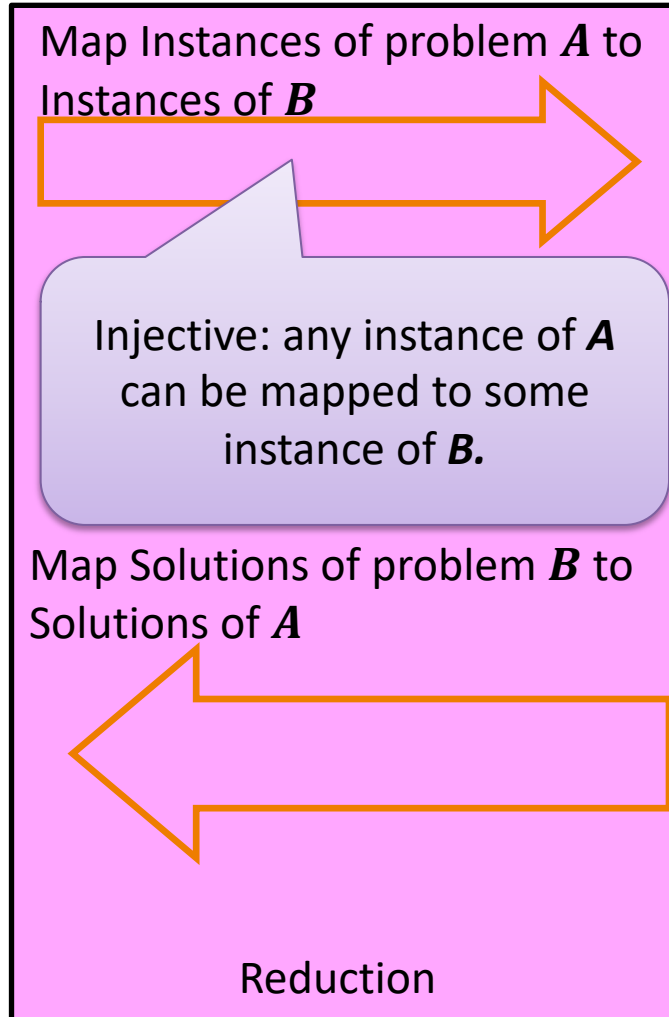
Problem we do know how to solve



Using any Algorithm
for B



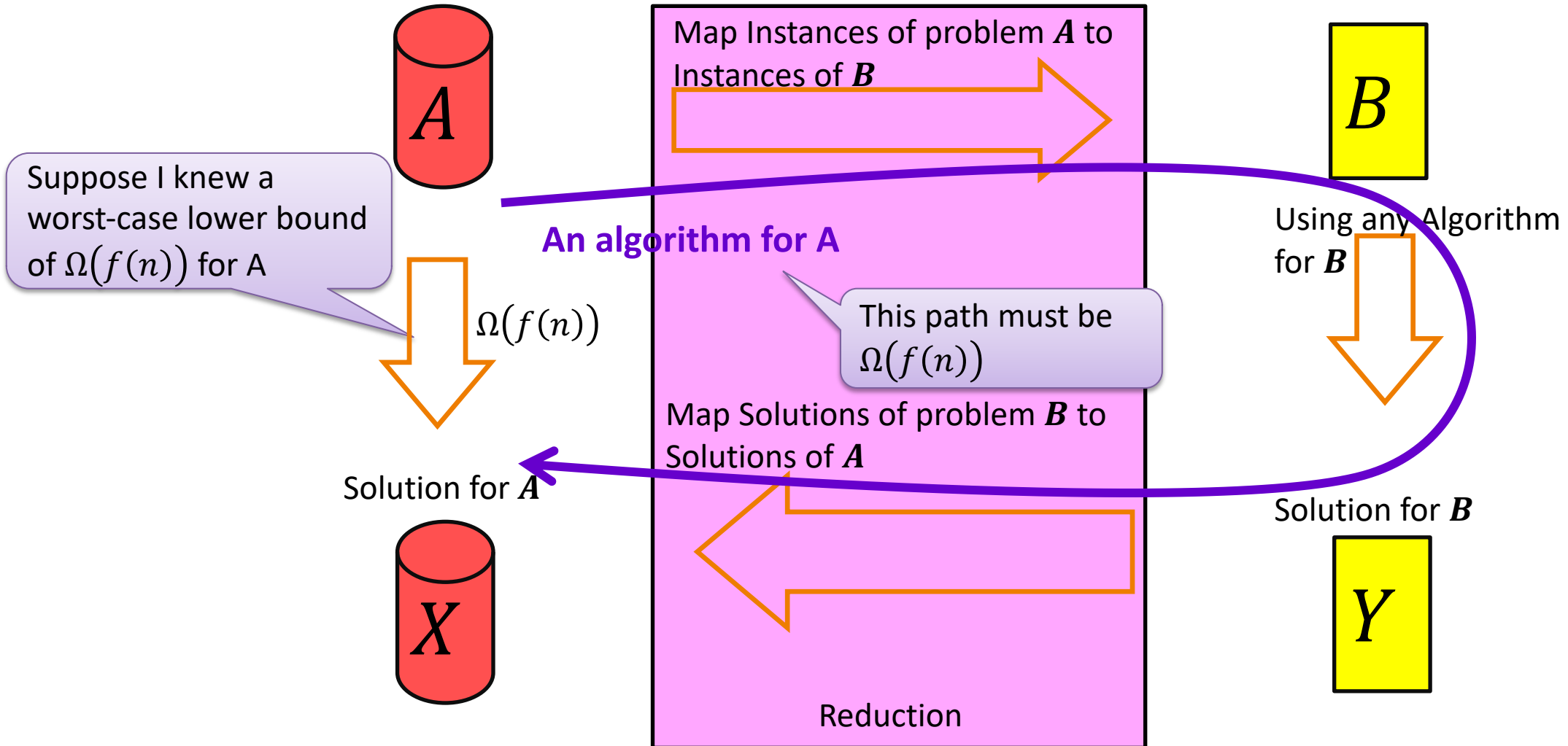
Solution for B



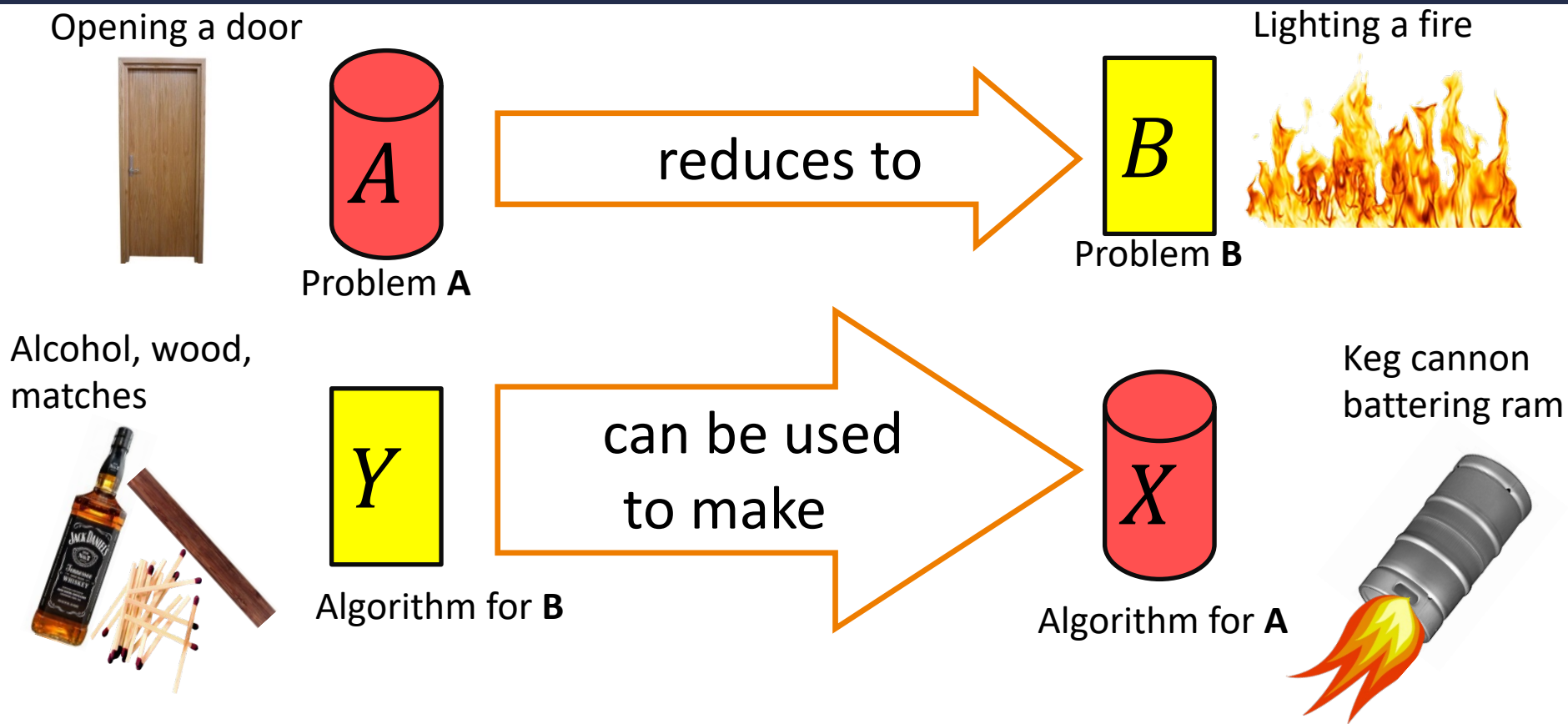
Worst Case Lower Bound

- Definition:
 - A **worst case lower bound** on a problem is an *asymptotic lower bound on the worst case running time* of any algorithm which solves it
 - If $f(n)$ is a worst case lower bound for problem A, then the worst-case running time of any algorithm which solves A must be $\Omega(f(n))$
 - i.e. for sufficiently large values of n , for every algorithm which solves A, there is at least one input of size n which causes the algorithm to do $\Omega(f(n))$ steps.
- Examples:
 - n is a worst-case lower bound on finding the minimum in a list
 - n^2 is a worst-case lower bound on matrix multiplication

Another use of Reductions



Worst-case lower-bound Proofs



A is not a harder problem than B

$$A \leq B$$

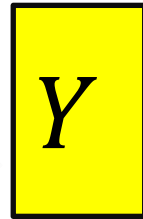
The name “reduces” is confusing: it is in the *opposite* direction of the making

Proof of Lower Bound by Reduction

To Show: Y is slow



1. We know X is slow (by a proof)
(e.g., X = some way to open the door)



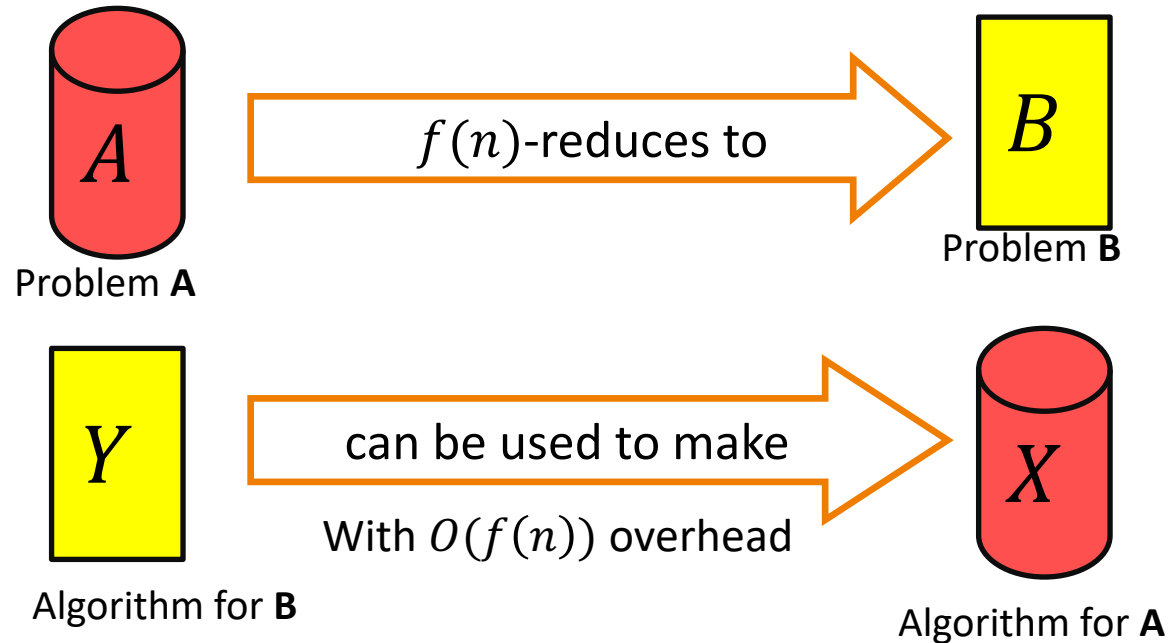
2. Assume Y is quick [toward contradiction]
(Y = some way to light a fire)



3. Show how to use Y to perform X quickly

4. X is slow, but Y could be used to perform X quickly
conclusion: Y must not actually be quick

Reduction Proof Notation



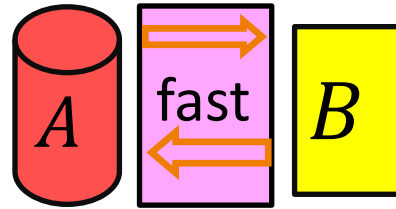
A is not a **harder problem than B**
 $A \leq B$

If A requires time $\Omega(f(n))$ time then B also requires $\Omega(f(n))$ time
 $A \leq_{f(n)} B$

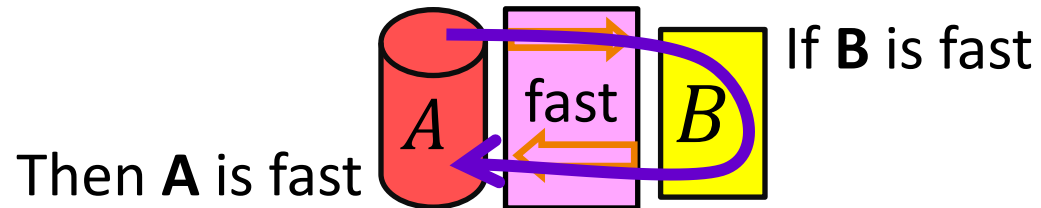
Or we could have solved A faster using B 's solver!

Two Ways to use Reductions

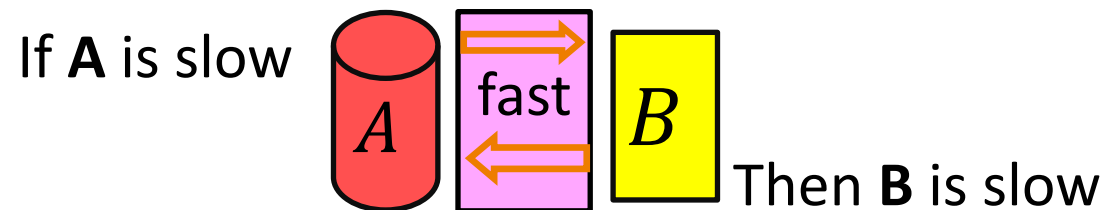
Suppose we have a “fast” reduction from **A** to **B**



1. A “fast” algorithm for **B** gives a fast algorithm for **A**

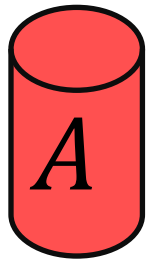


2. If we have a worst-case lower bound for **A**, we also have one for **B**



Bipartite Matching Reduction

Problem we don't know how to solve

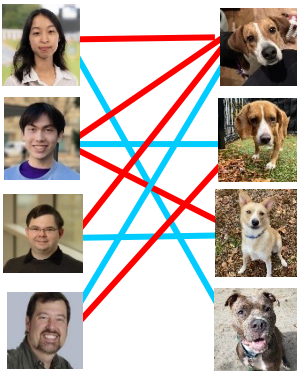


Bipartite Matching



Then this is fast

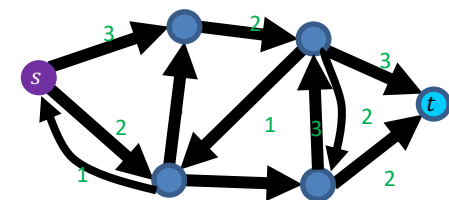
Solution for *A*



Problem we do know how to solve



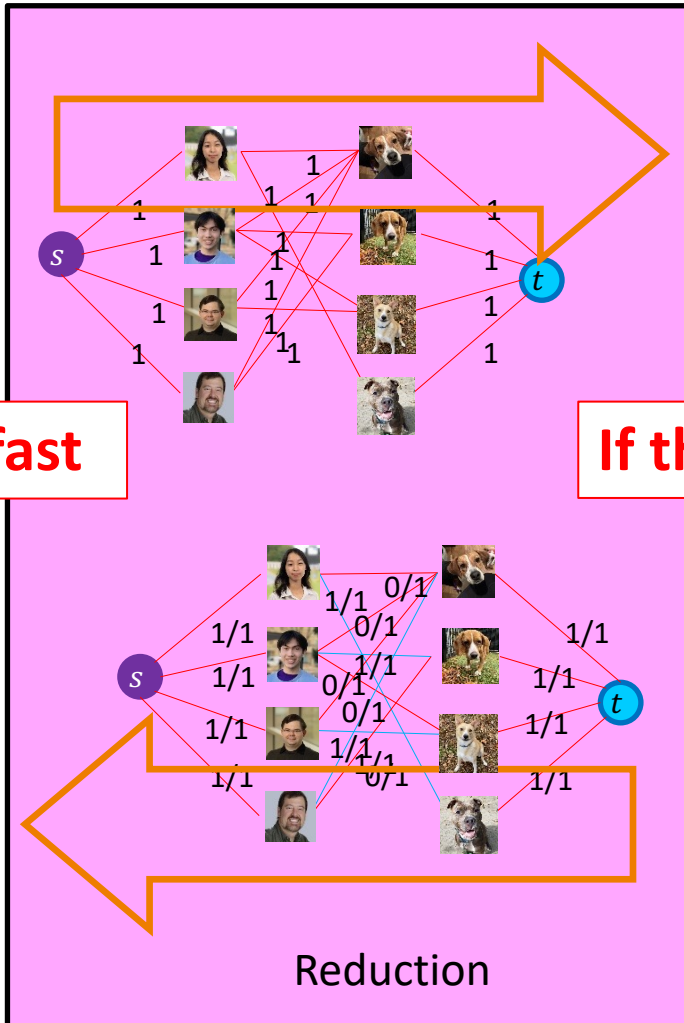
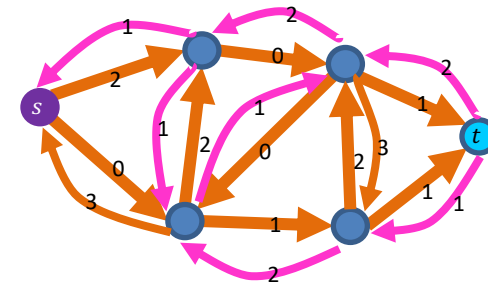
Max Flow



Ford Fulkerson

If this is fast

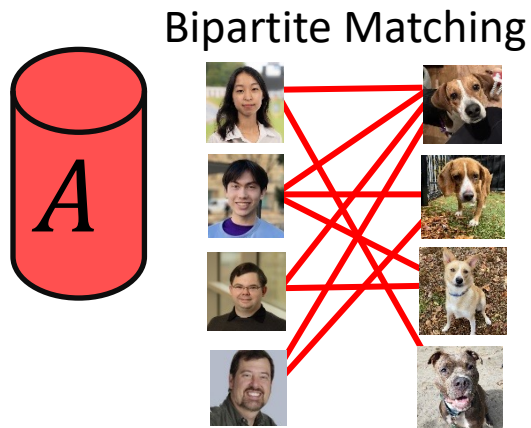
Solution for *B*



Reduction

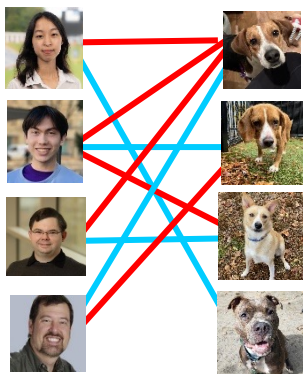
Bipartite Matching Reduction

Problem we don't know how to solve

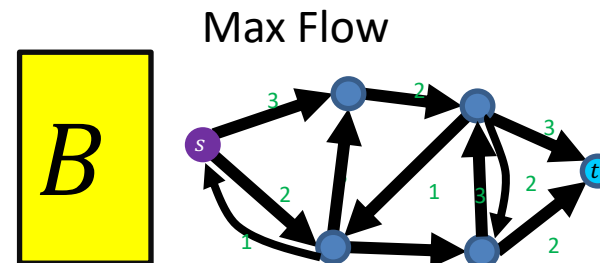


If this is slow

Solution for A

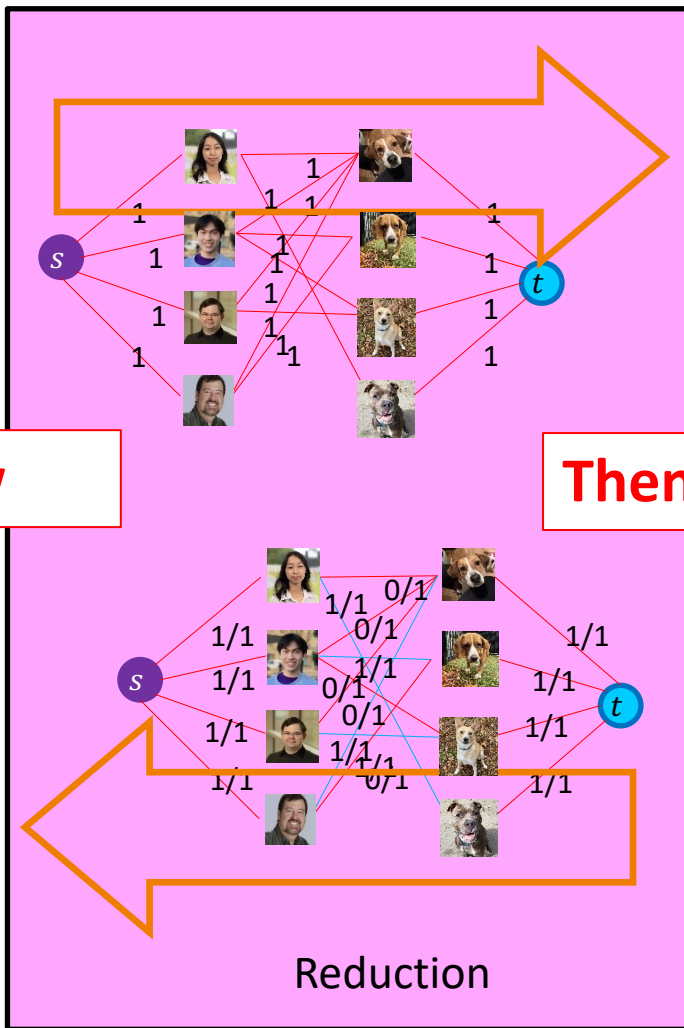
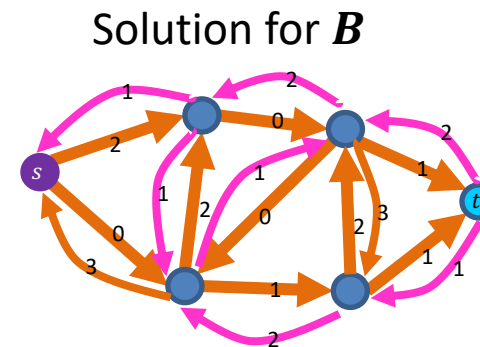


Problem we do know how to solve



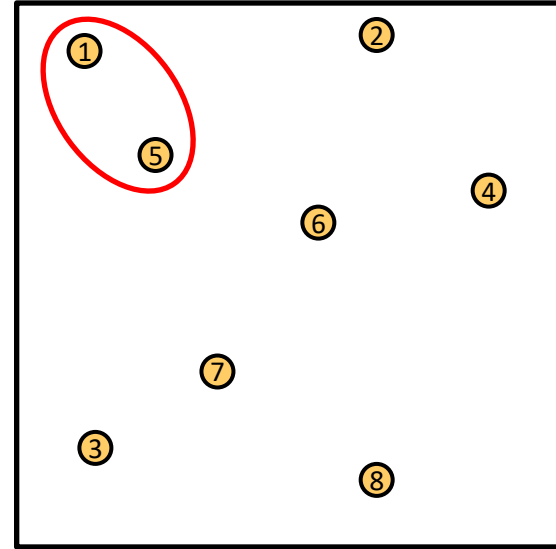
Ford Fulkerson

Then this is slow



Worst-case Lower-Bound Using Reductions

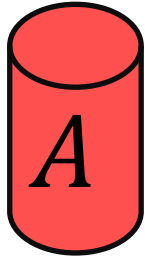
- Closest Pair of points
 - D&C algorithm: $\Theta(n \log n)$
 - Can we do better?



- Idea: Show that doing closest pair in $o(n \log n)$ enables an impossibly fast algorithm for another problem

Reductions for Lower-Bounds

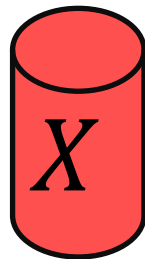
Problem we know is "Hard"



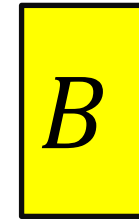
and this must be slow,

"Hard" means this must be slow

Solution for A



Problem we want to show is "Hard"



then this this can't be fast!

Some Algorithm for B

Solution for B



Quickly Map Instances of problem A to Instances of B

If this is quick,

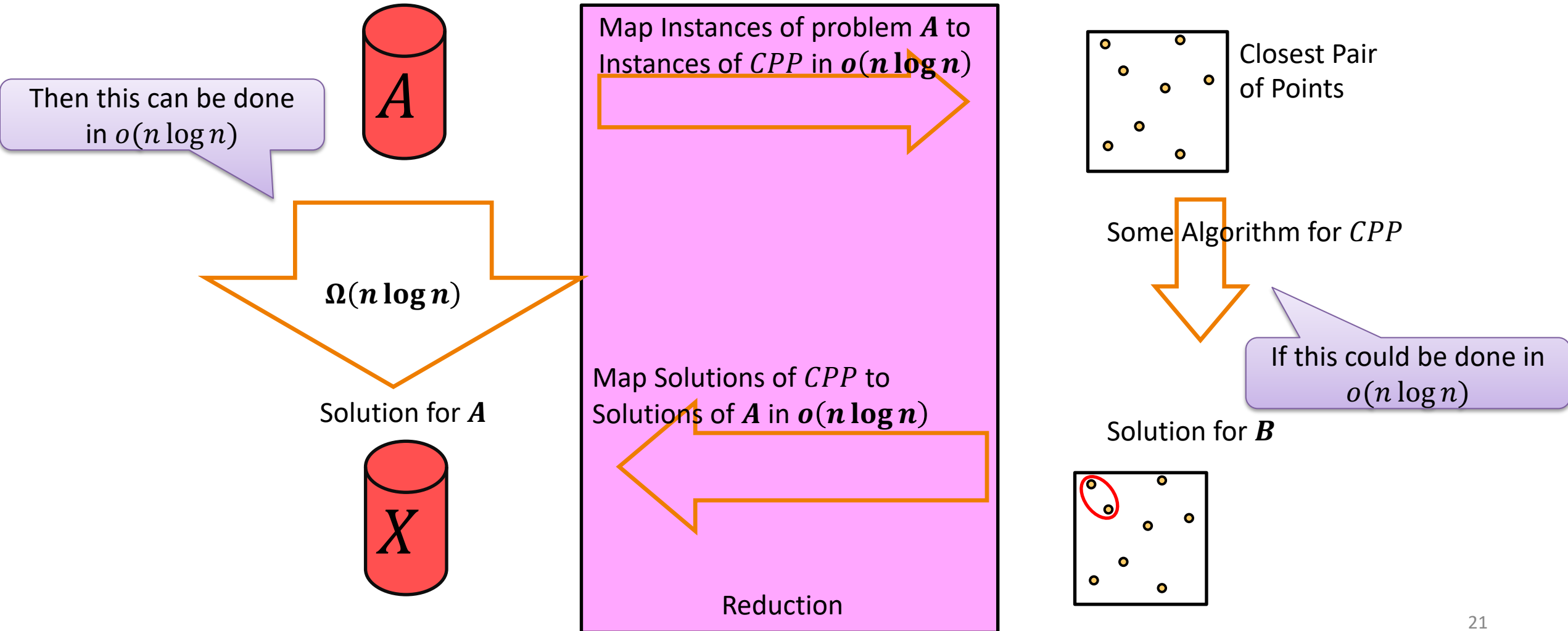
Quickly Map Solutions of problem B to Solutions of A

and this is quick,
Reduction

Reductions for Lower-Bound on CPP

Problem we know is $\Omega(n \log n)$

Problem we want to show is $\Omega(n \log n)$



A “Hard” Problem: Element Uniqueness

- Input:

| | | | | | | | | |
|-----|-----|-----|-----|-----|-----|-----|-----|-------------|
| 113 | 901 | 555 | 512 | 245 | 800 | 018 | 121 | True |
|-----|-----|-----|-----|-----|-----|-----|-----|-------------|

- A list of integers

- Output:

| | | | | | | | | |
|-----|-----|-----|------------|-----|------------|-----|-----|--------------|
| 103 | 801 | 401 | 323 | 255 | 323 | 999 | 101 | False |
|-----|-----|-----|------------|-----|------------|-----|-----|--------------|

- **True** if all values are unique, **False** otherwise

- Can this be solved in $O(n \log n)$ time?

- Yes! Sort, then check if any adjacent elements match

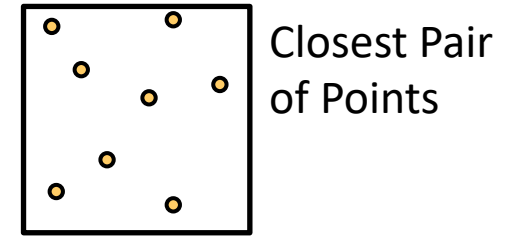
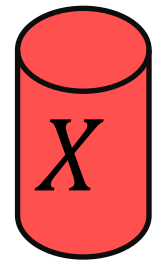
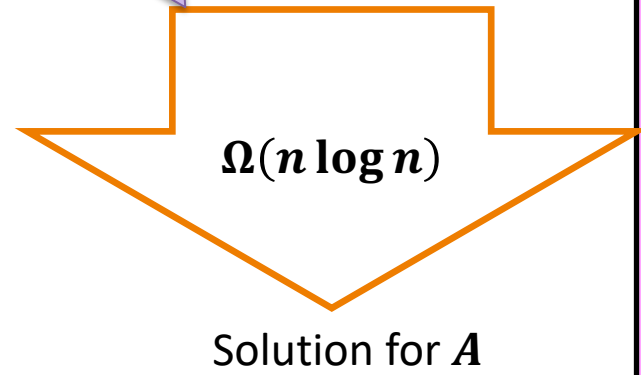
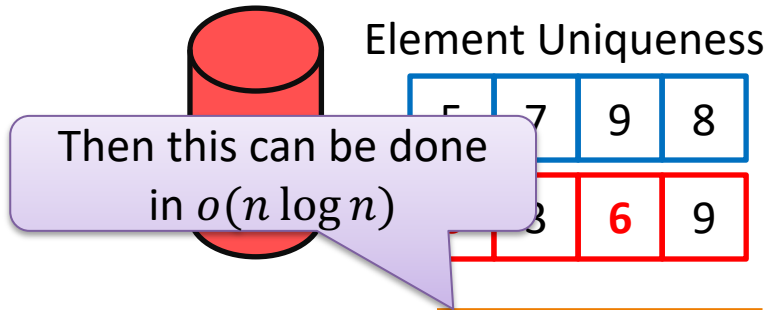
- Can this be solved in $o(n \log n)$ time?

- No! (we’re going to skip this [Proof](#))

Reductions for Lower-Bound on CPP

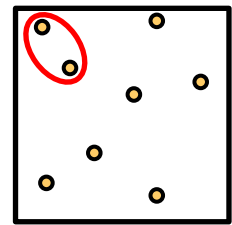
Problem we know is $\Omega(n \log n)$

Problem we want to show is $\Omega(n \log n)$



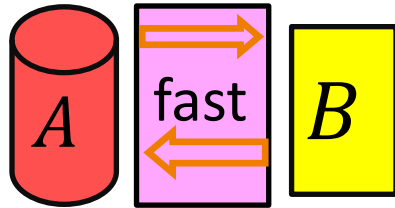
Some Algorithm for *CPP*

If this could be done in $o(n \log n)$

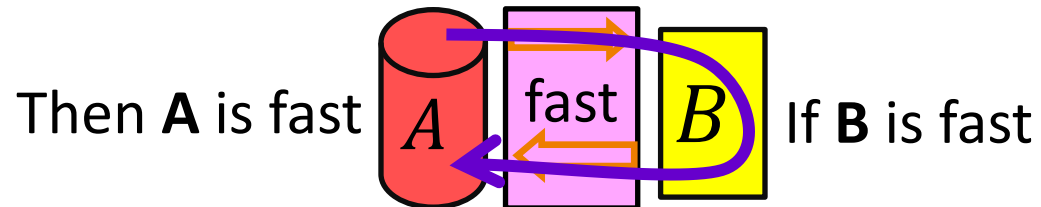


Two Ways to use Reductions

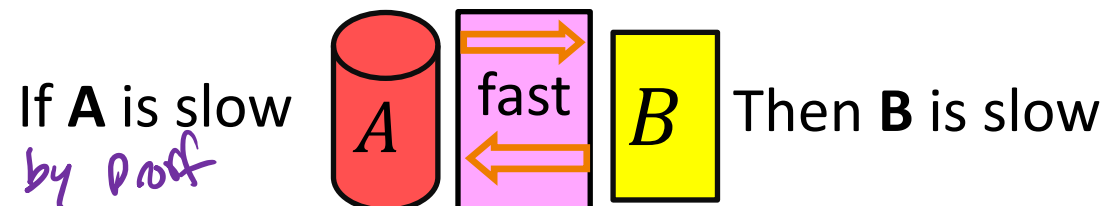
Suppose we have a “fast” reduction from **A** to **B**



1. A “fast” algorithm for **B** gives a fast algorithm for **A**



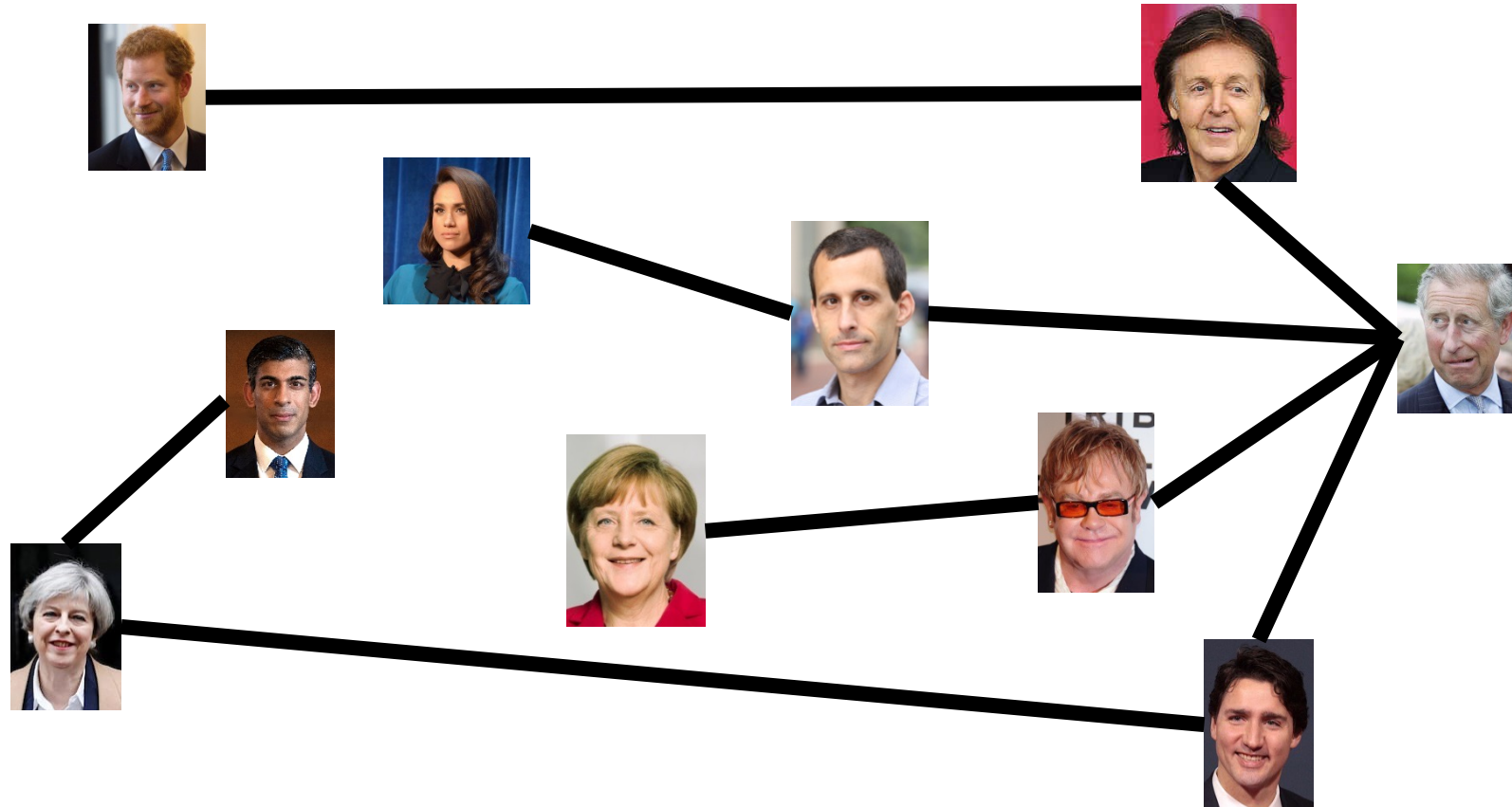
2. If we have a worst-case lower bound for **A**, we also have one for **B**



Party Problem



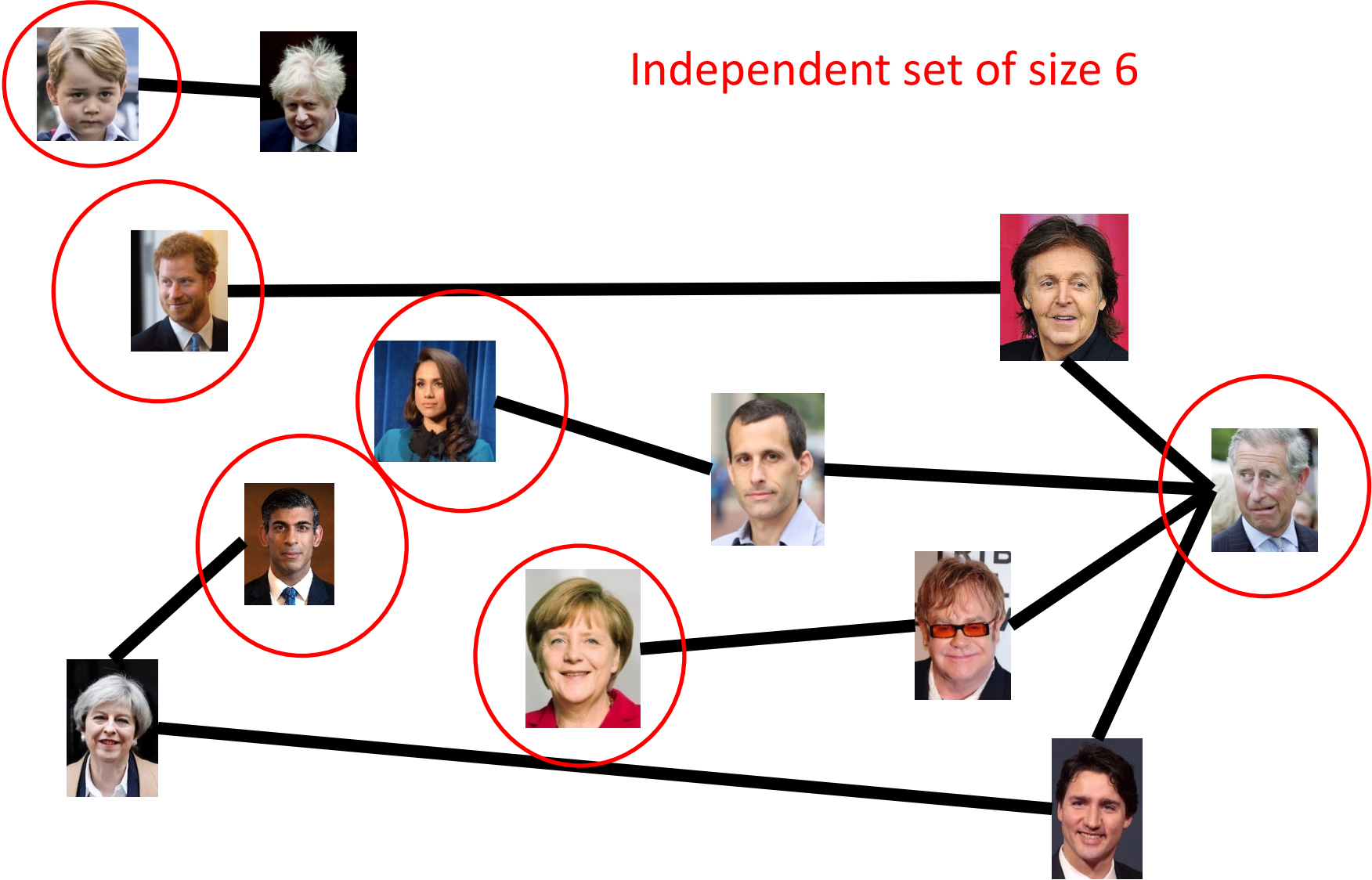
Draw Edges between people who don't get along
Find the maximum number of people who get along



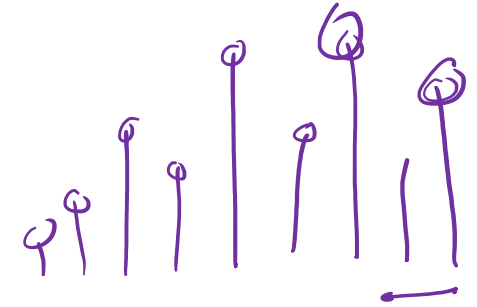
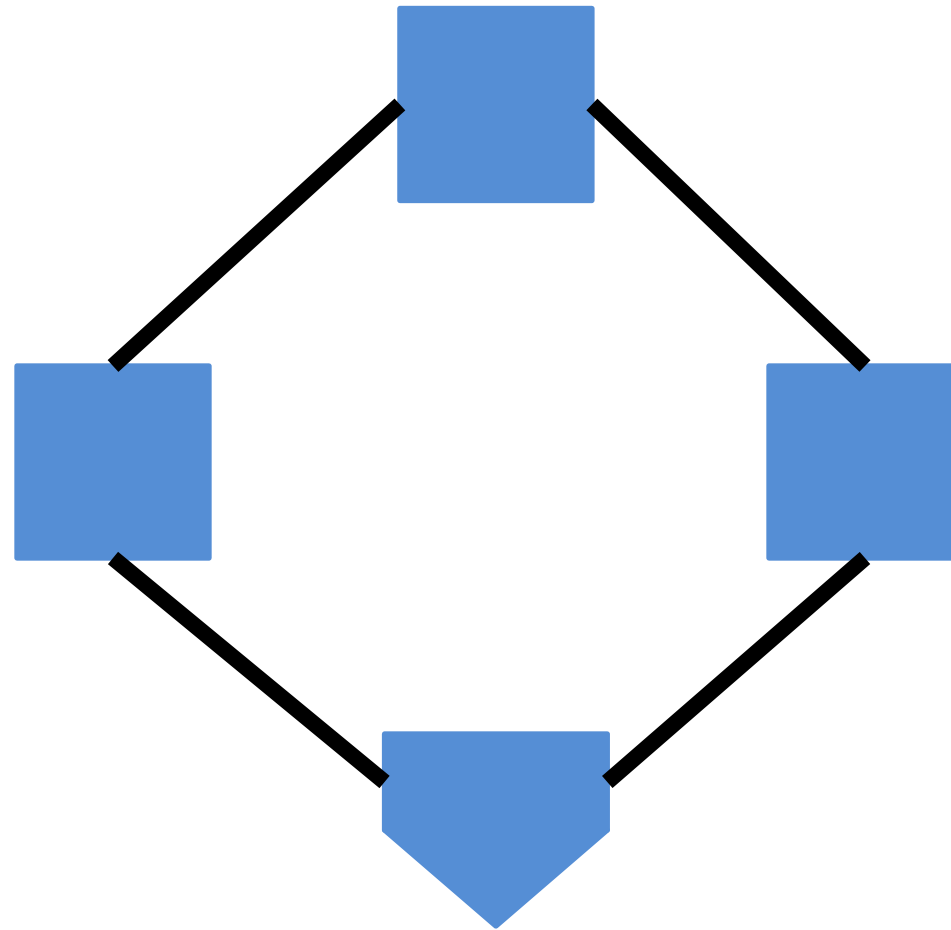
Maximum Independent Set

- Independent set: $S \subseteq V$ is an independent set if no two nodes in S share an edge
- Maximum Independent Set Problem: Given a graph $G = (V, E)$ find the maximum independent set S

Example

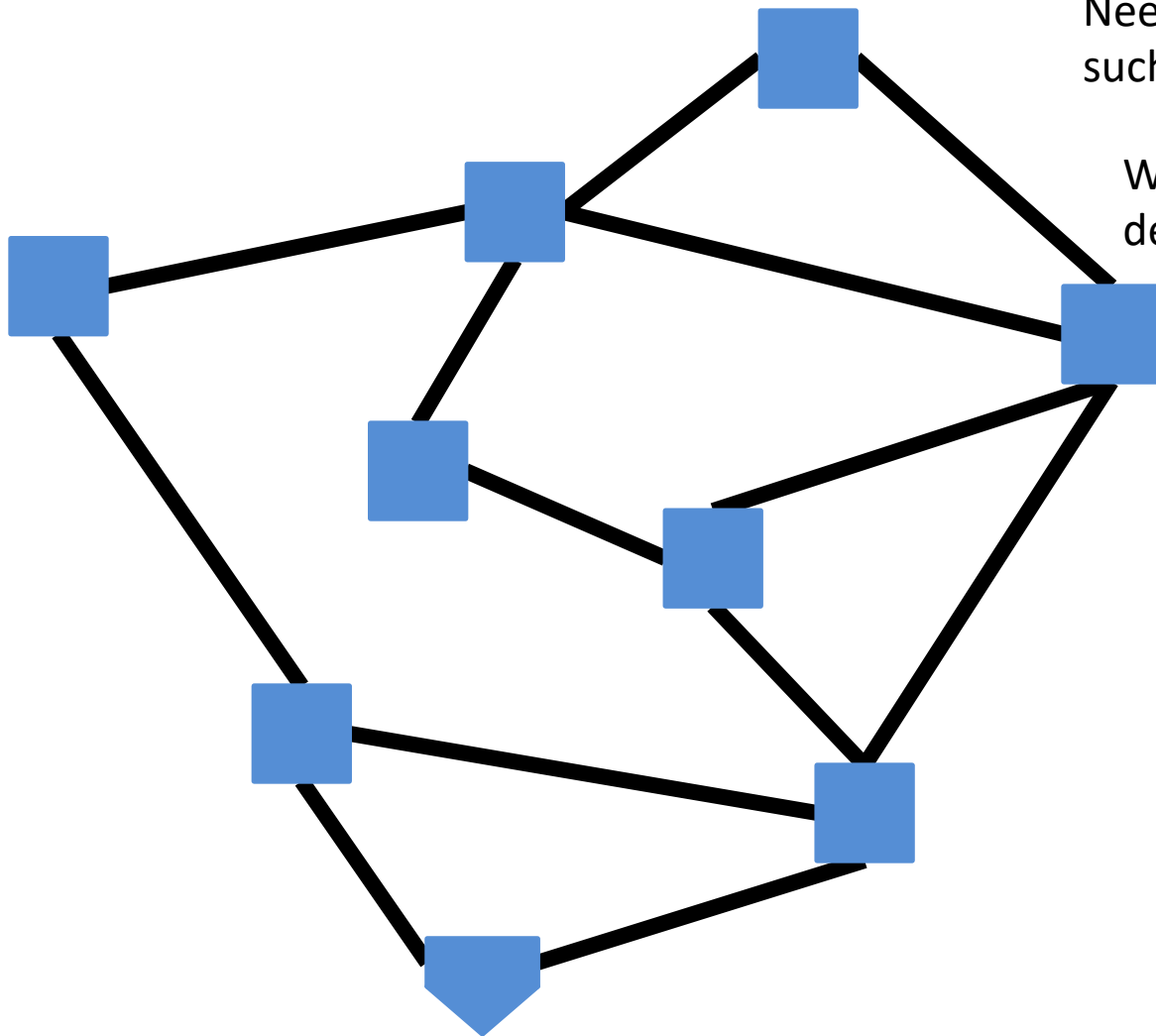


Generalized Baseball



$$\begin{aligned}n &\in O(n^2) \\ n^2 &\in \Theta(n^2) \\ n^3 &\in \Omega(n^2)\end{aligned}$$

Generalized Baseball



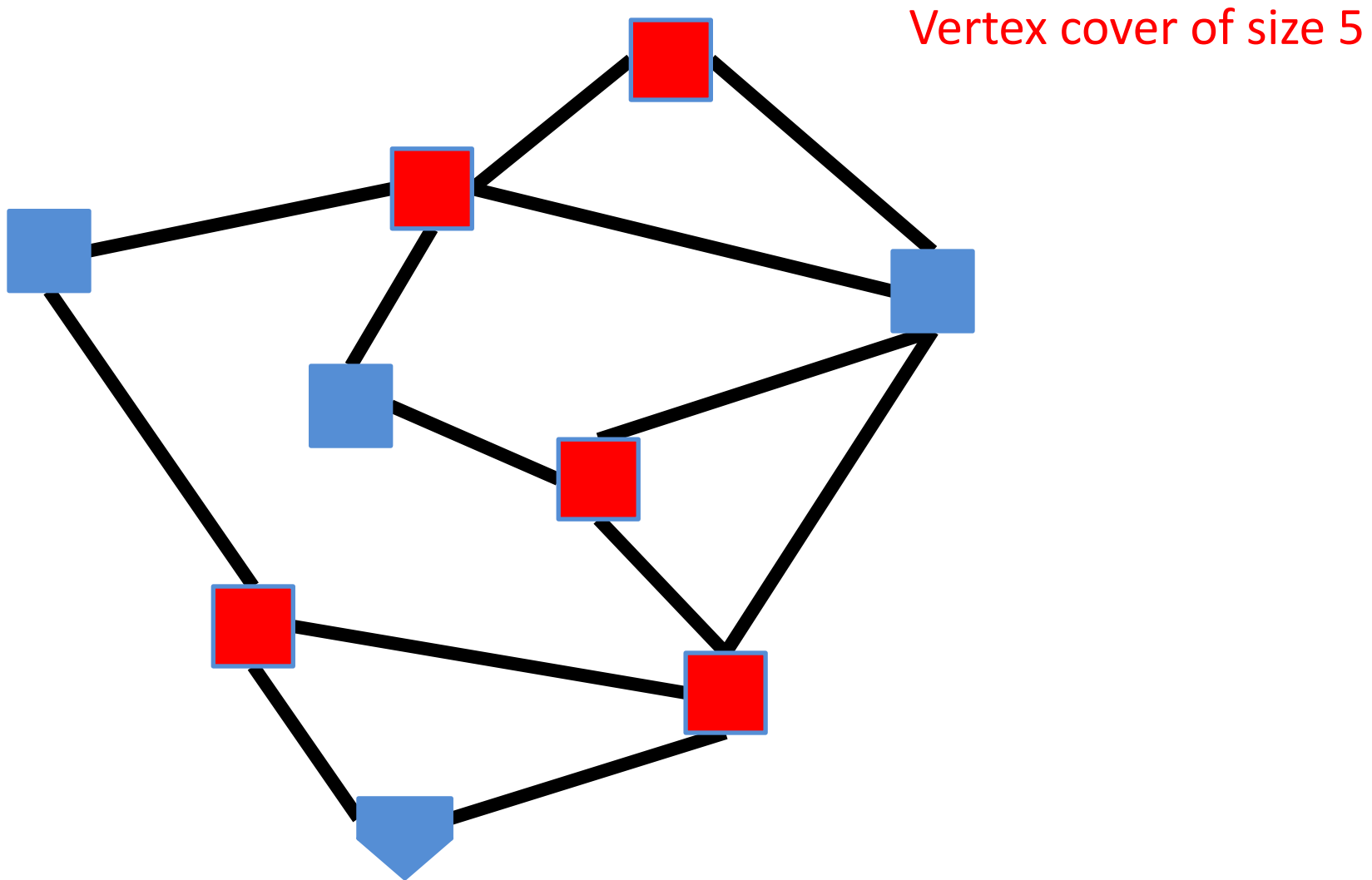
Need to place defenders on bases such that every edge is defended

What's the fewest number of defenders needed?

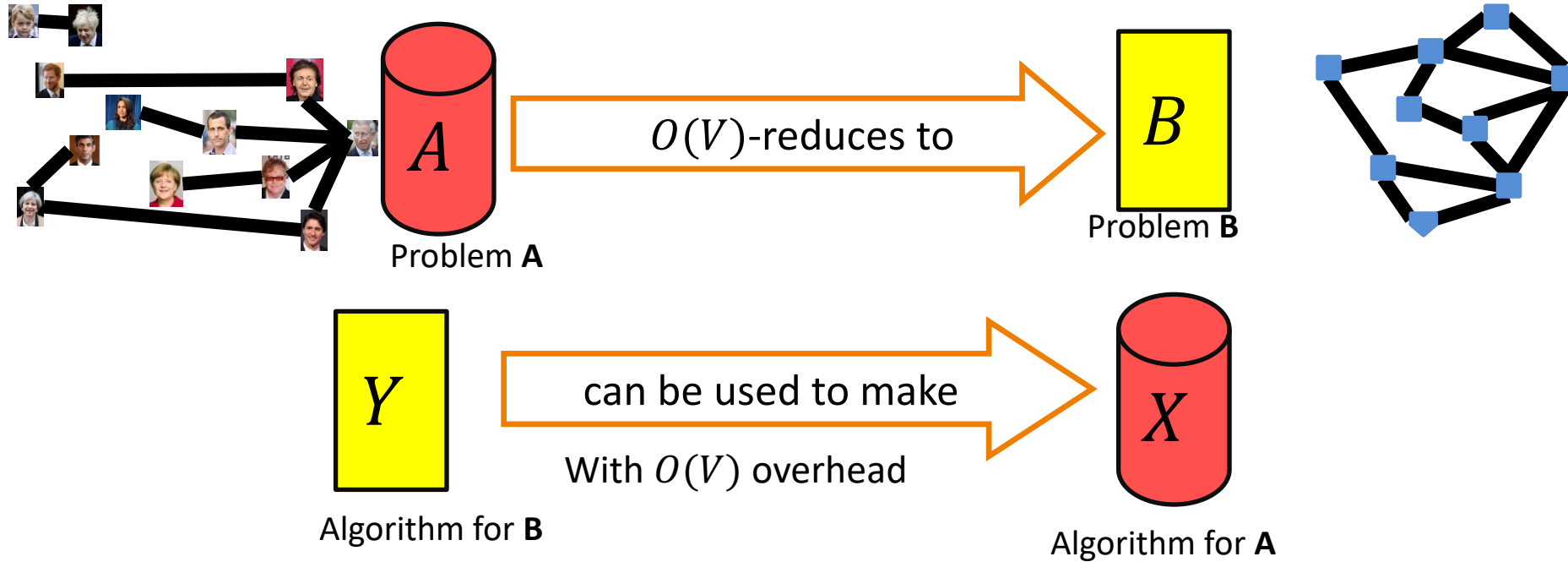
Minimum Vertex Cover

- Vertex Cover: $C \subseteq V$ is a vertex cover if every edge in E has one of its endpoints in C
- Minimum Vertex Cover: Given a graph $G = (V, E)$ find the minimum vertex cover C

Example



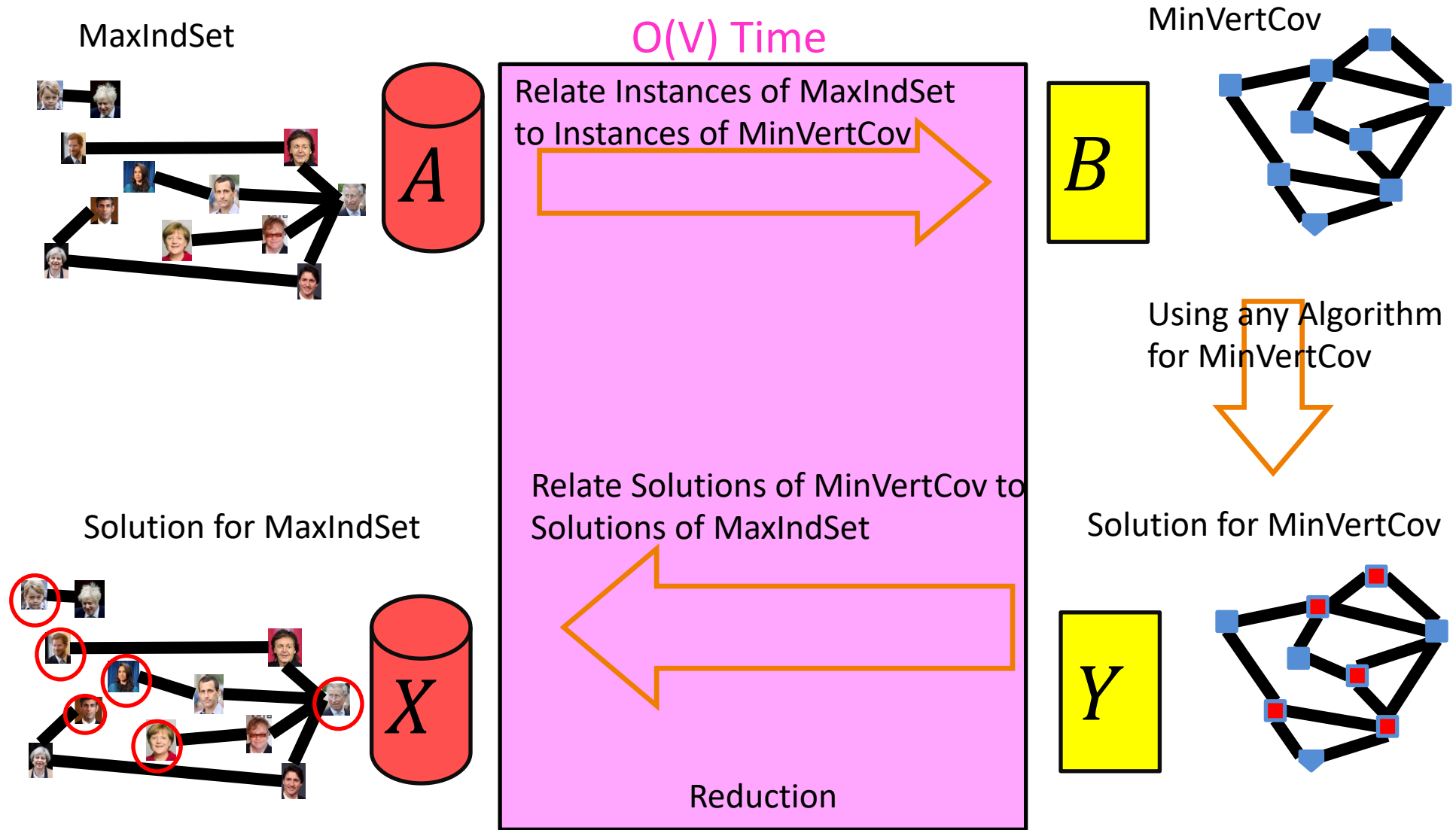
MaxIndSet \leq_V MinVertCov



If **A** requires time $\Omega(f(n))$ time then **B** also requires $\Omega(f(n))$ time

$$A \leq_V B$$

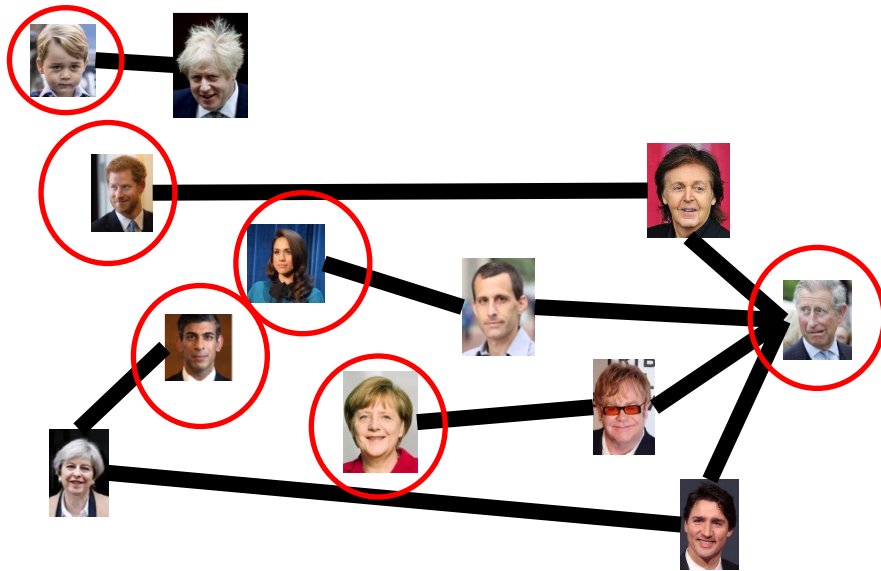
We need to build this Reduction



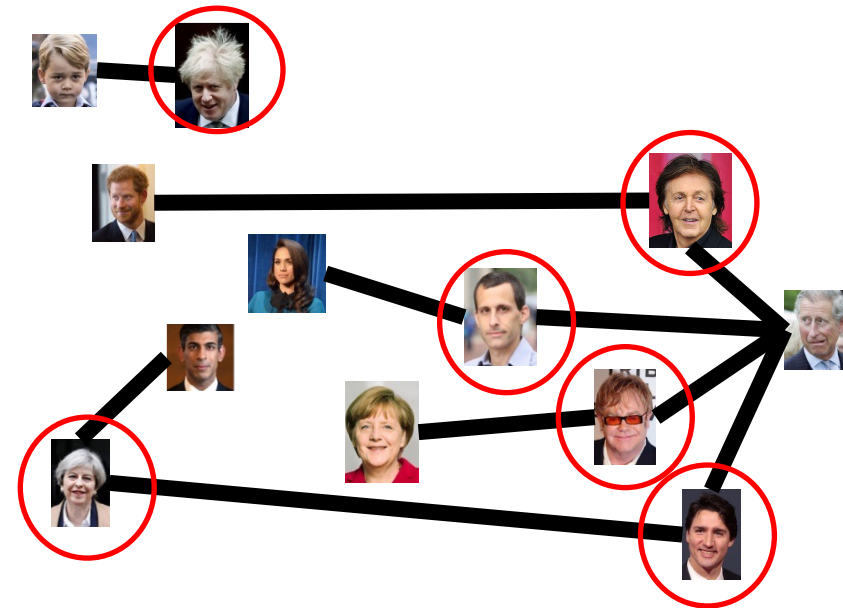
Reduction Idea

S is an independent set of G iff $V - S$ is a vertex cover of G

Independent Set



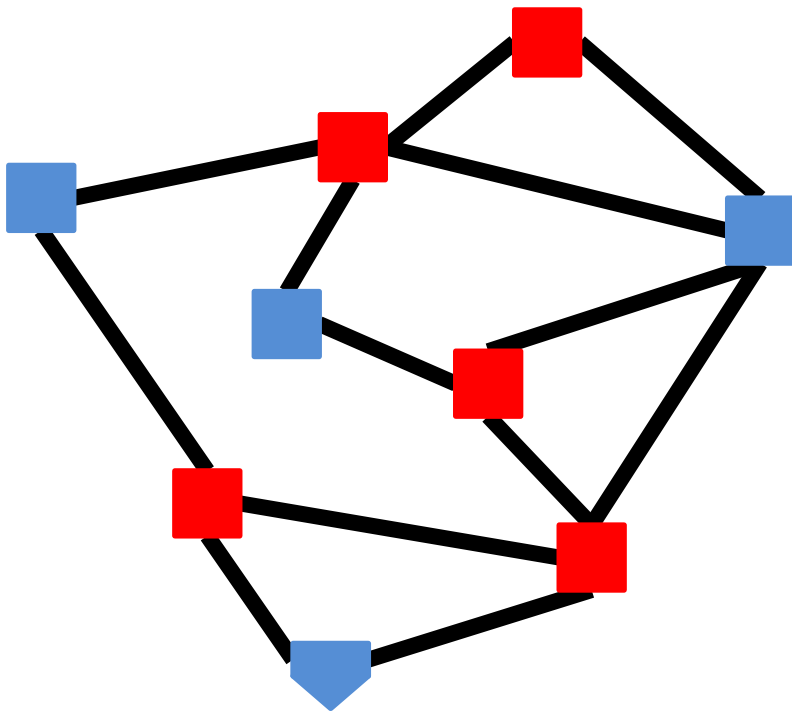
Vertex Cover



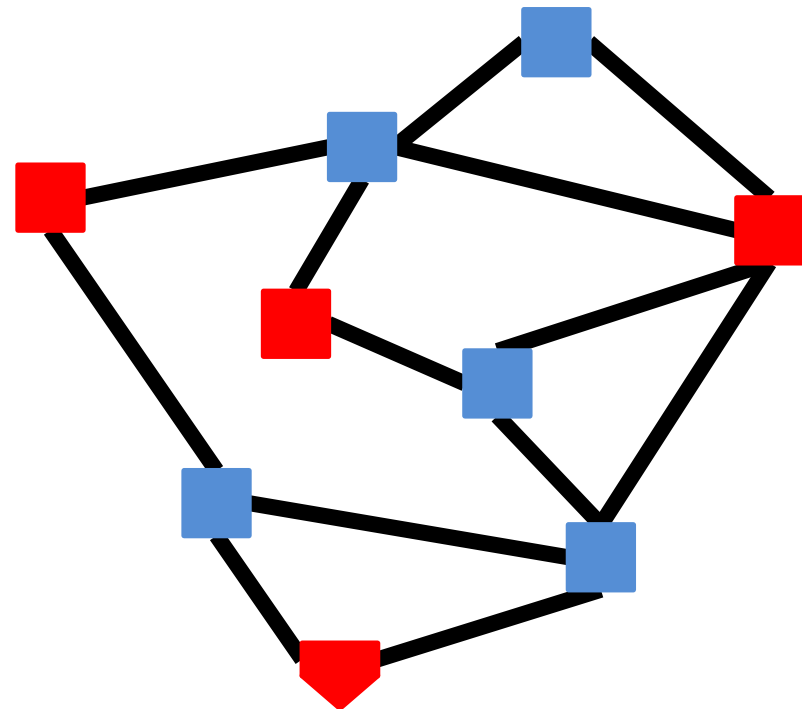
Reduction Idea

S is an independent set of G iff $V - S$ is a vertex cover of G

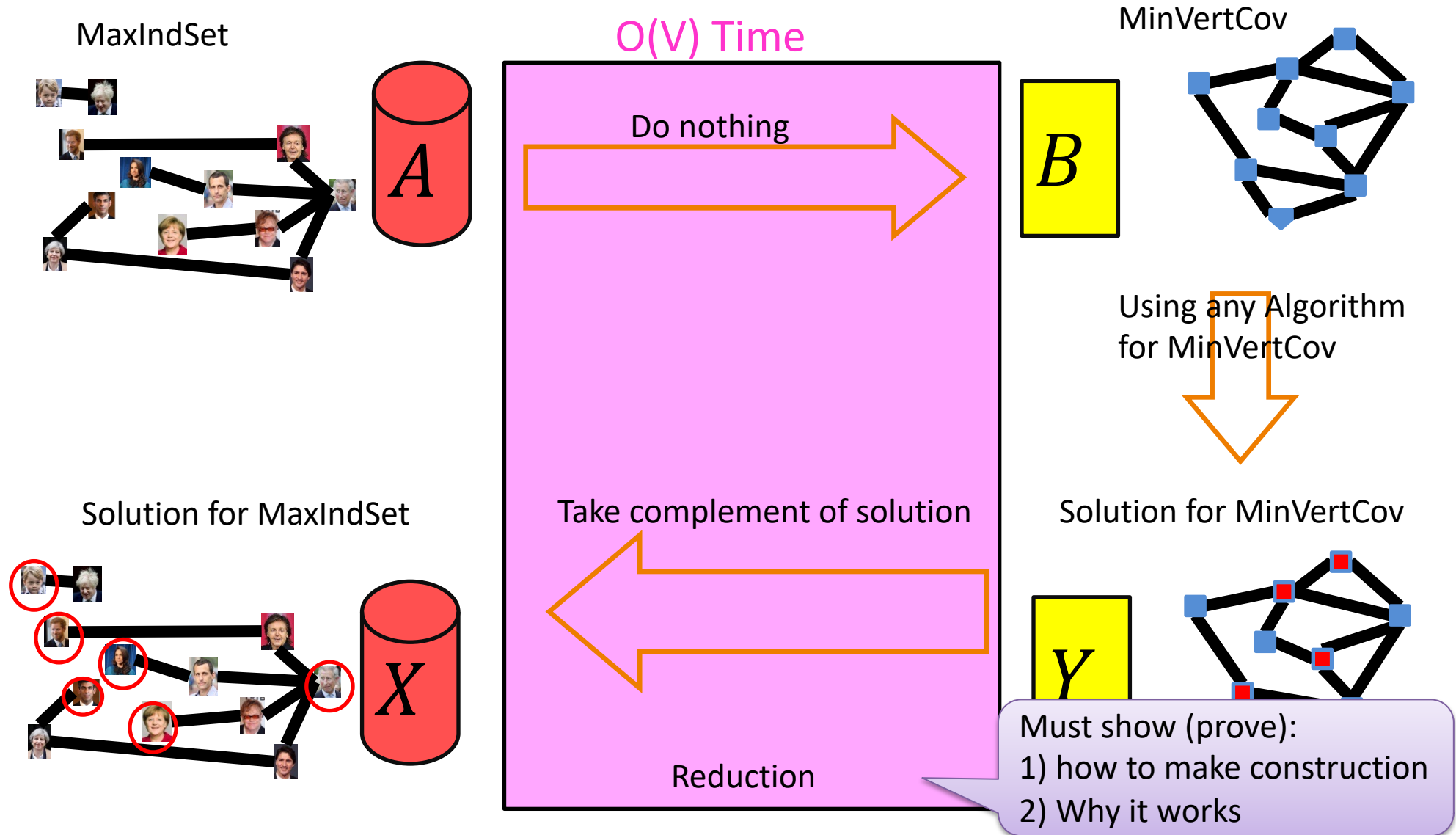
Vertex Cover



Independent Set



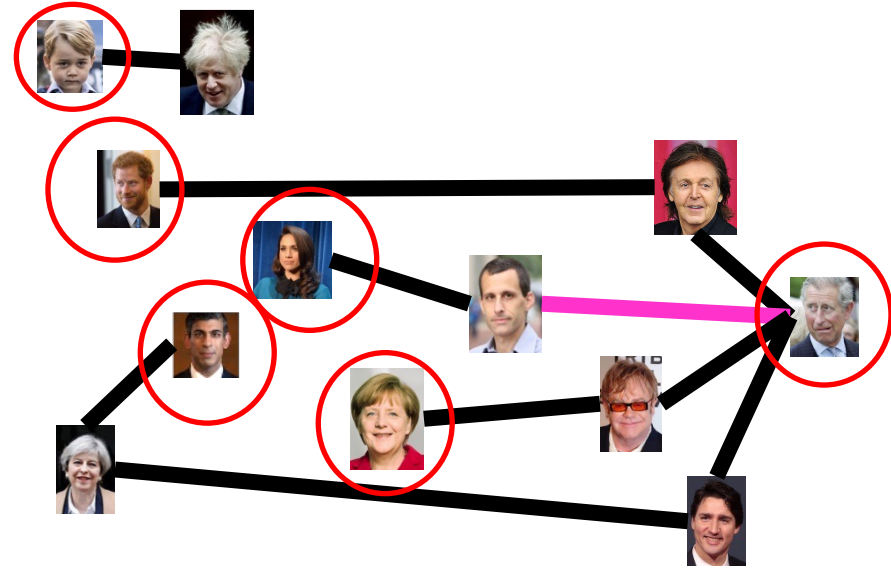
MaxVertCov V -Time Reducible to MinIndSet



Proof: \Rightarrow

S is an independent set of G iff $V - S$ is a vertex cover of G

Let S be an independent set



Consider any edge $(x, y) \in E$

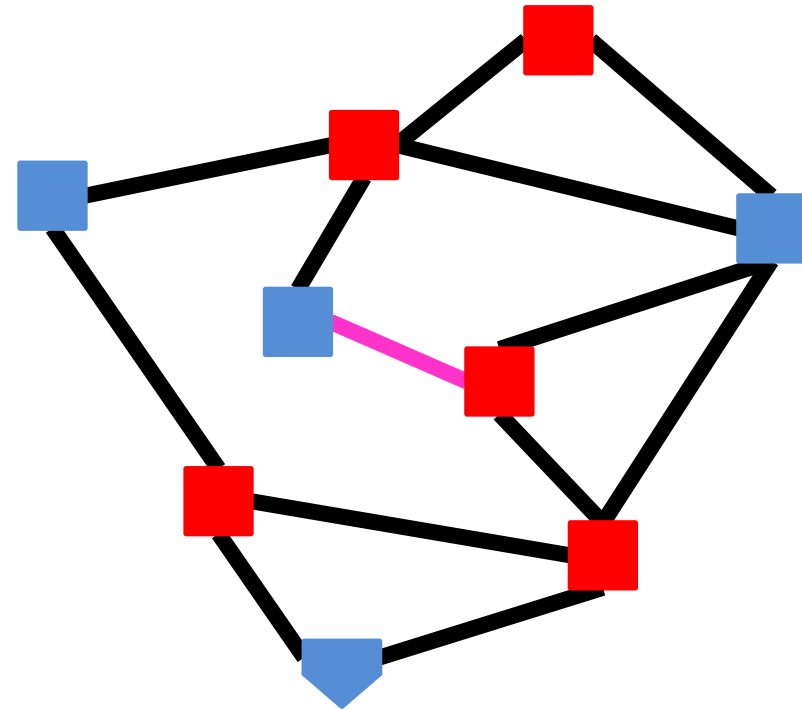
If $x \in S$ then $y \notin S$, because otherwise S would not be an independent set

Therefore $y \in V - S$, so edge (x, y) is covered by $V - S$

Proof: \Leftarrow

S is an independent set of G iff $V - S$ is a vertex cover of G

Let $V - S$ be a vertex cover



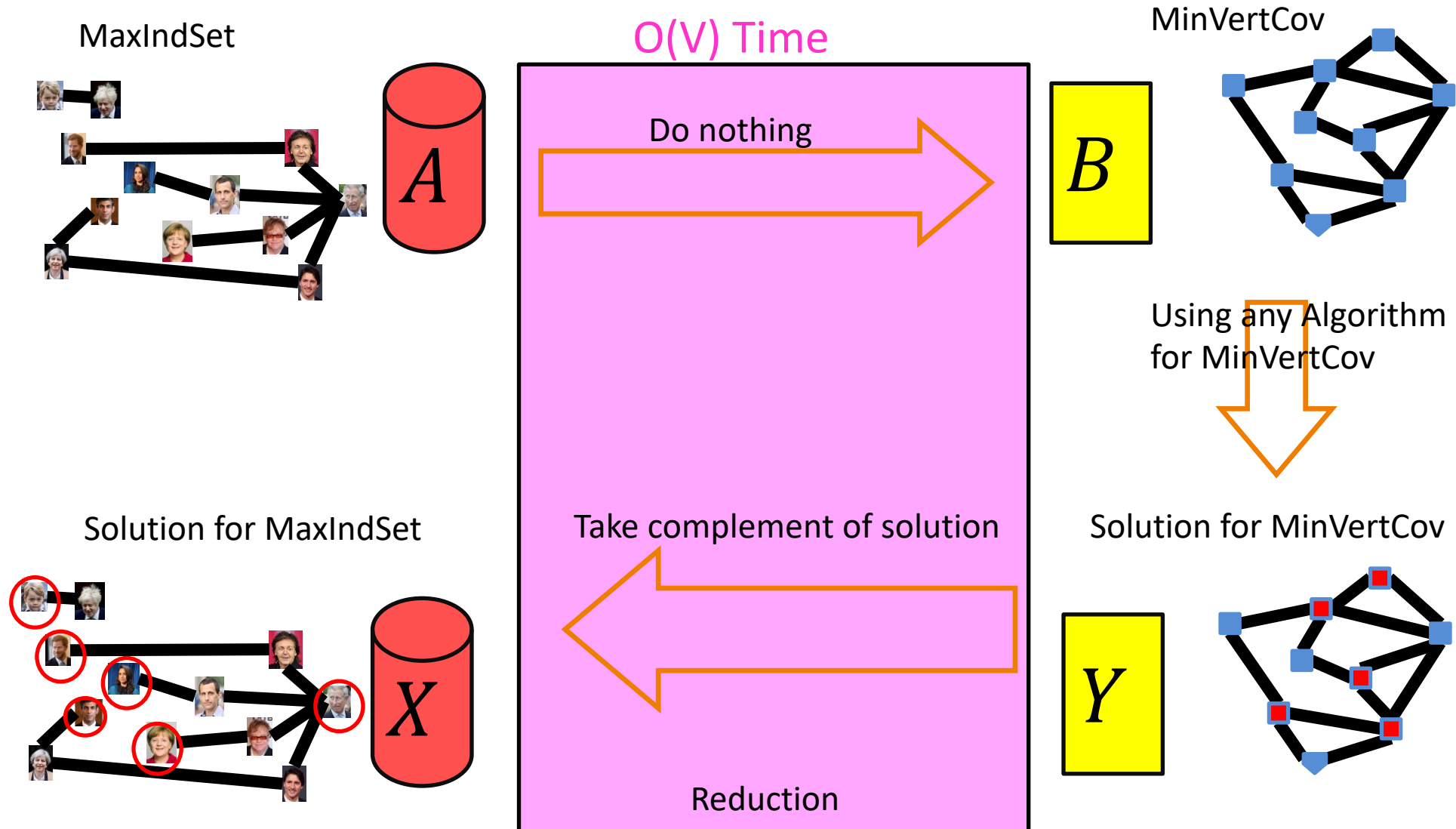
Consider any edge $(x, y) \in E$

At least one of x and y belong to $V - S$, because $V - S$ is a vertex cover

Therefore x and y are not both in S ,

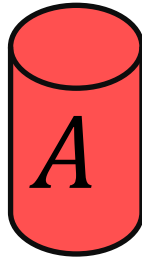
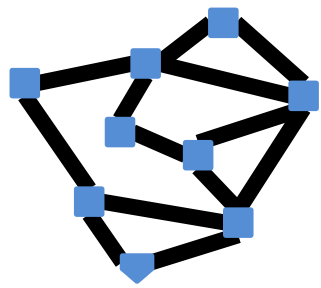
No edge has both end-nodes in S , thus S is an independent set

MaxVertCov V -Time Reducible to MinIndSet

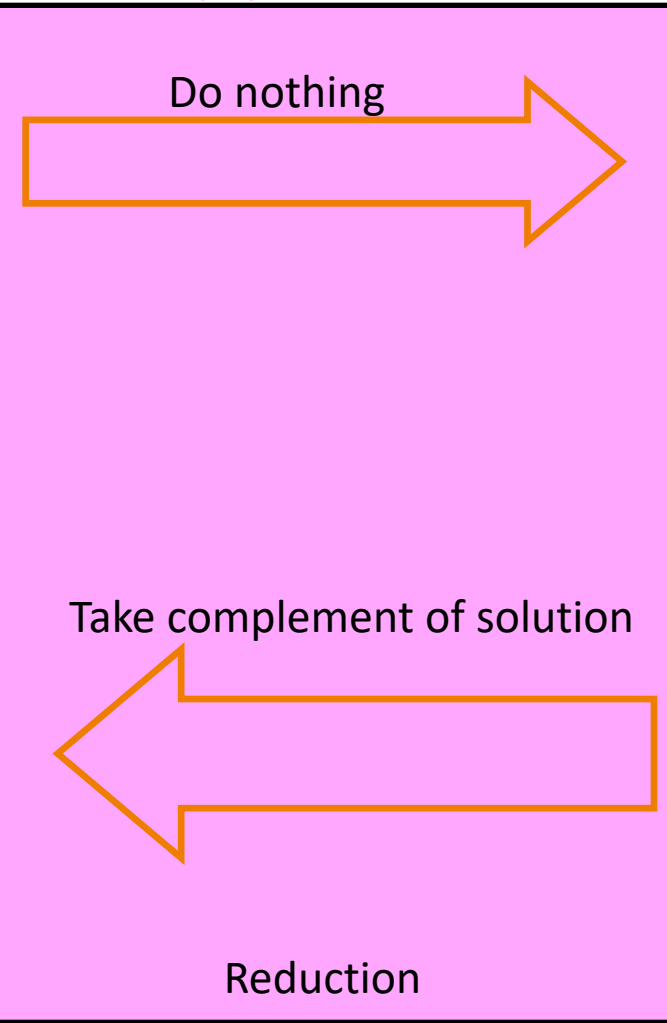


MaxIndSet V -Time Reducible to MinVertCov

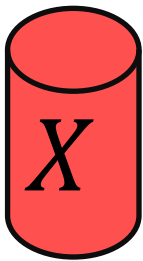
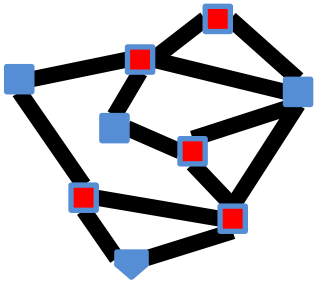
MinVertCov



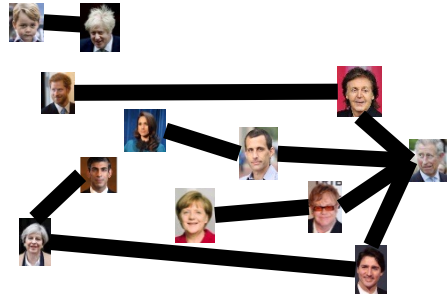
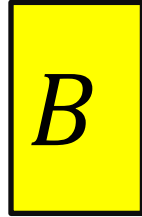
$O(V)$ Time



Solution for MinVertCov



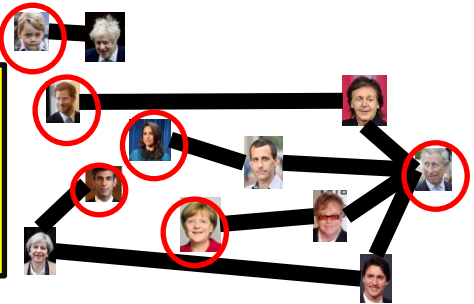
MaxIndSet



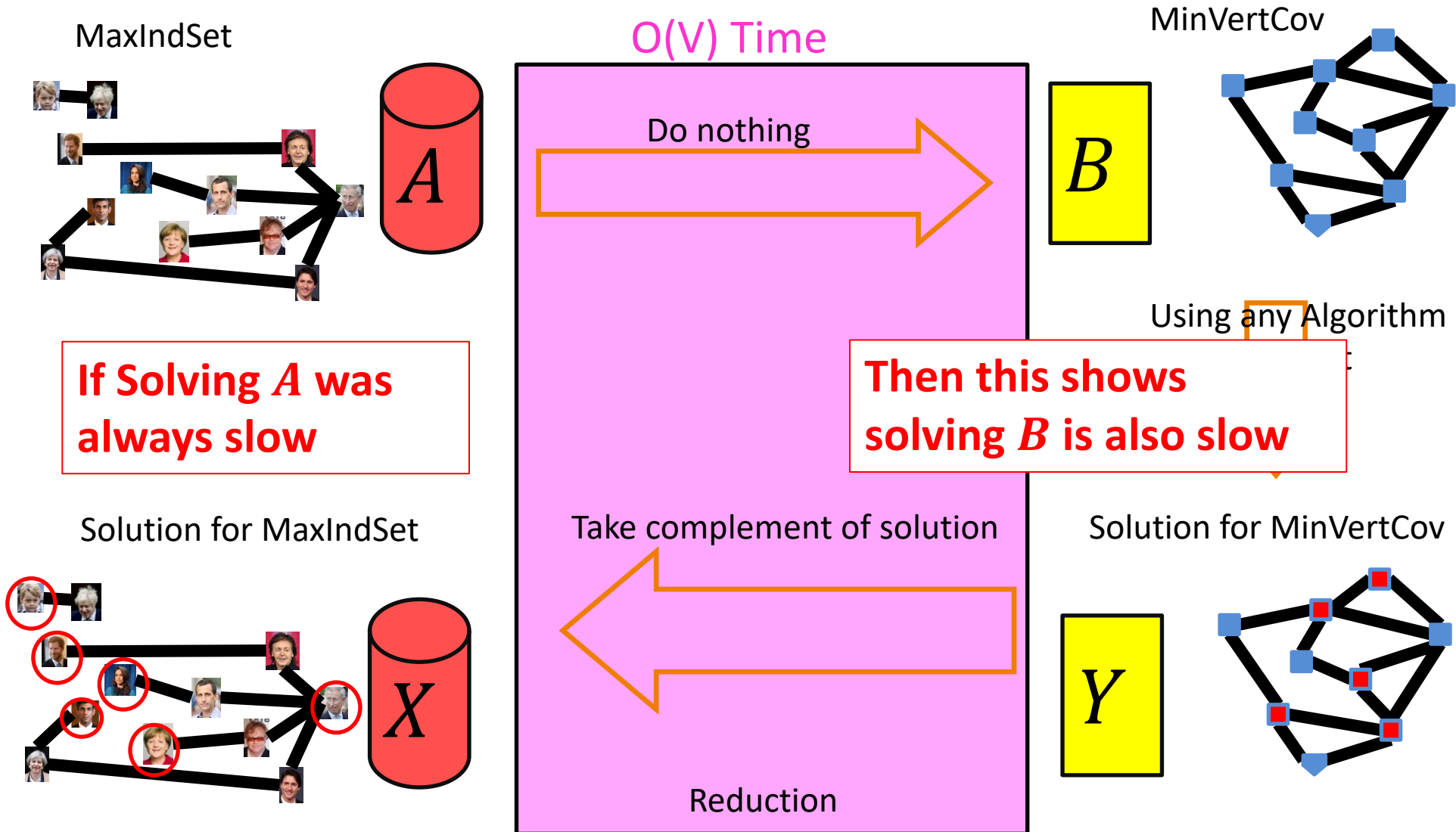
Using any Algorithm for MaxIndSet



Solution for MaxIndSet

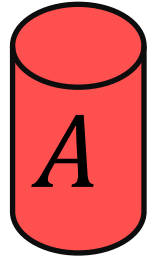
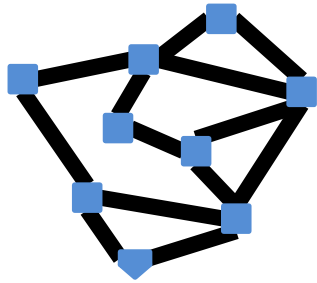


Corollary



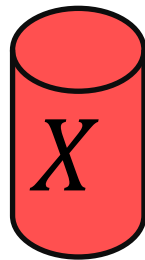
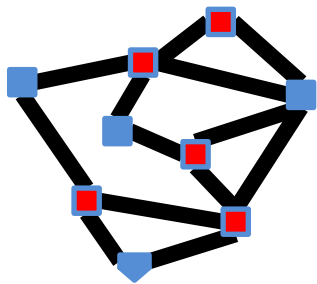
Corollary

MinVertCov



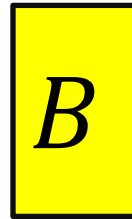
If Solving *A* was always slow

Solution for MinVertCov

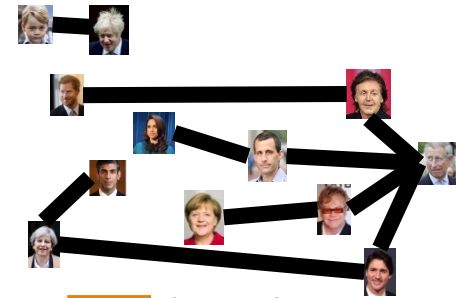


$O(V)$ Time

Do nothing



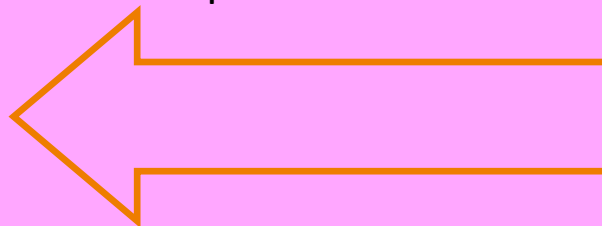
MaxIndSet



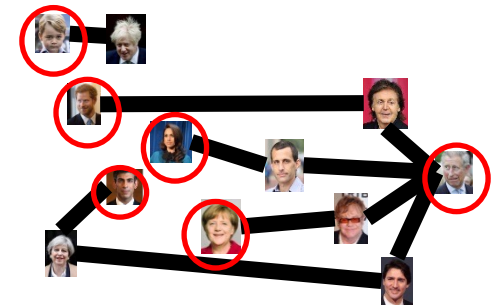
Using any Algorithm

Then this shows solving *B* is also slow

Take complement of solution



Solution for MaxIndSet



Reduction

Conclusion

- MaxIndSet and MinVertCov are either both fast, or both slow
 - Spoiler alert: We don't know which!
 - (But we think they're both slow)
 - Both problems are NP-Complete
 - More in DMT2